Numerical Method for Modeling the Turbofan Engine Tonal Fan BPF Noise Generation and Propagation Accounting the SAS Complex Acoustic Impedance

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Abstract

Noise reduction issues in the developed world receive an increasing attention, which is reflected in a great tightening of the noise level requirements. For the practical solution of this problem authors propose a new high-performance numerical modeling method of three-dimensional tonal noise acoustic field generated by the fan as a bladed machine. The method is based on solving a boundary value problem for Fourier transformed convective wave equation with complex variables in a Cartesian coordinate system in the arbitrary domain with impedance boundary conditions by finite volume method. The noise source is set in the form of sound power on the surface near the rotor that bounds the area of the vortex perturbations (pseudosound). Sound power is determined by acoustic-vortex method. There are shown examples of the method validation and application.

Keywords: acoustic-vortex method; blade passing frequency; complex acoustic impedance; pressure pulsations; SAS; tonal noise.

1. Introduction

Noise reduction, in order to minimize negative impact of noise on human activity in the open space, residential, office and industrial buildings, cultural and religious institutions, car interiors, trains, aircraft and even spacecraft cabin becomes the most urgent problem as the noise influences essentially on the human health and productivity. These issues in the developed world receive increasing attention, which is reflected in a significant tightening of the requirements for limiting the noise level in accordance with ISO standards [1,2] . Numerical modeling of the computer cooling fan acoustics becomes an engineering problem of current interest [3] as well as for train fans [4] and modern aircraft turbofan engines [5].

The nature of aerodynamic noise generation in the axial fan described in a very practical book of A. Guedel [6]. He noted that the fan noise spectrum comprises the tonal and broadband noise components. Tonal components at frequencies that are multiples of the rotor blade passing frequency (BPF) usually dominates in the spectrum and defines the total sound power level. In axial fans, where the circular velocity Mach number at the rotor periphery is below 0.5, noise generation relates to the case of a dipole source following the aeroacoustic analogy introduced by M.J. Lighthill [7]. N. Curle [8], J.E. Flowcs Williams and D.L. Hawkings [9] formulated the theoretical basis for methods of the bladed machine aerodynamic noise computation. The dipole nature of noise generation and radiation is caused by forces acting on the rotor and stator blades from the gas flow pressure. The analytical formulation of these processes is based on the formalization [10] of W.R.

Sears and represents the radiated sound in the form of the so-called spinning modes [11]. J.M. Tyler and T.G. Sofrin [12] showed that spinning modes attenuated exponentially in a long pipe at low Mach flow velocity.

Currently computational fluid dynamics and acoustics methods widely developed that proposed to determine the fan acoustic radiation[13,14]. They are mainly based on the application of Lighthill equation and aeroacoustic analogy like FWH equation or the Kirchhoff theorem application [15]. In such methods the decomposition problem, i.e., separation of acoustic and vortex (pseudosound) modes in the area of the oscillation source is not resolved.

For the practical solution of the tonal noise problem authors propose a new high-performance numerical modeling method of three-dimensional acoustic field at blade passing frequencies, its higher and combined harmonics generated in bladed machines of computer devices, air conditioning systems, turbofan aircraft engines.

The method is based on solving a boundary value problem for Fourier transformed convective wave equation with complex variables in a Cartesian coordinate system in the arbitrary domain with impedance boundary conditions by the finite volume method. The noise source is set in the form of sound power on the surface near the rotor that bounds the area of the vortex perturbations (pseudosound). The sound power is determined by acoustic-vortex method [16]. In the acoustic-vortex method the noise is represented with a local derivative of the vortex mode pressure [17]. It identifies the source, pressure pulsations, and noise propagation in the near field as a direct result of numerical simulation.

2. Method

2.1. Governing Equation and Boundary Conditions

The proposed numerical method of modeling 3-dimensional acoustic fields is based on solving boundary value problems in the field of arbitrarily complex geometry with respect to the Fourier image of the pressure perturbations p.

Governing equation

Governing equation describes the propagation of sound in a thermodynamically uniform

$$\left(ik + M_j \frac{\partial}{\partial x_j} \right)^2 p = \frac{\partial^2 p}{\partial x_j^2} + f \tag{1}$$

steady flow. Flow parameters varies in the space with the Mach number vector M_j [18]. Here $k = \omega / c$, where ω - frequency c - sound speed.

Boundary conditions

The boundary condition at the wall can be written in the form of Myers relation [19] as:

$$iku_n = \left(ik + M_j \frac{\partial}{\partial x_j} - \frac{\partial M_l}{\partial x_j} n_j n_l \right) \frac{p}{\rho c Z} , \tag{2}$$

where $u_n = n_j u_j$ - the Fourier image of the velocity perturbation directed to the normal to the wall n_j, Z - specific complex impedance of wall or sound-absorbing structure (SAS), in general, dependent on the local Mach number and the boundary layer parameters.

On the perfectly reflecting wall boundary condition (2) becomes $u_n = 0$. On the external boundaries of the computational domain the non-reflective boundary condition is specified as a Sommerfeld sound emission into unlimited space, here modified to take into account space non-uniformity of sound wave parameters in accordance with the concept [20] :

$$ik\rho c u_n = \left(ik + M_j \frac{\partial}{\partial x_j} - \frac{\partial M_l}{\partial x_j} n_j n_l \right) p + \frac{i}{2k} \Delta_n p , \tag{3}$$

where Δ_n - two-dimensional Laplace operator in the plane, orthogonal to the normal vector n_j.

To close the boundary conditions (2, 3) the Fourier transform of momentum conservation law projection on the normal is used, that can be written as follow:

$$\left(ikn_j + \frac{\partial M_l}{\partial x_j} n_l \right) u_j + \left(M_l \frac{\partial u_j}{\partial x_l} + \frac{1}{\rho c} \frac{\partial p}{\partial x_j} \right) n_j = 0 \tag{4}$$

2.2. Acoustic Source

The acoustic source is modeled in the form of boundary conditions at ambient fan control surface S remote from its rotor by a distance at which attenuation of vortex or pseudo-sound mode is almost complete and the oscillations are primarily acoustic (usually this distance is about 1.5 of the chord length of rotor blades

[18,21]. This boundary condition can be written in the form of a right invariant

$$J_+(x) = p + \rho c u_j n_j , \tag{5}$$

in which the pressure and velocity perturbations are determined by either:
From a single 3-dimensional calculation of unsteady turbulent flow in the fan taking into account the rotor-stator interaction by moving meshes technique [22];
Simple iterations of the energy equation that can be written in the integral form [16,21] (6) with known sound source power defined by acoustic-vortex method and

- sound wavelength considerably larger the rotor radius - $R / \lambda \ll 1$;
- Mach number in the region bounded by the S is much less than 1 - $M \ll 1$.

$$\frac{1}{\sqrt{2\pi}} \iint\limits_{S} \int\limits_{-\infty}^{+\infty} p(\omega - \xi) u_n(\xi) d\xi \cdot dS = W_l \delta(\omega - \omega_l) , \tag{6}$$

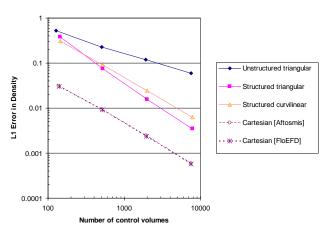where W_l - sound source power at the BPF harmonic l.

2.3. Computational Grid

The problem (1-4) is solved by the finite volume method on Cartesian grid, agreed with the boundary of computational domain automatically fitted to the body shape and features of the solution through the h-refinement procedure. **Fig. 1** shows a fragment of a body immersed in a Cartesian grid.
Fig. 2 outlines the behavior of the integral L1 norm of local truncation error for model scalar transfer equation in an annular region for structured and unstructured triangular and curvilinear sequence refined grids [23].

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Fig. 1: Cartesian immersed-body grid

Fig. 2: L1 norm of local truncation error for sequence of refined meshes. The lower (dashed) curves were obtained on a Cartesian grid

It can be seen that the smallest error of approximation is reached on a Cartesian grid.
Besides Cartesian grids enables the integration of computational technology developed in the CAD system [24].

2.3. Parallel Iterative Algorithm for SLAE Solver

The parallel iterative algorithm for solving the system of linear algebraic equations (SLAE) derived as a result of discretization of equations (1 - 4). The initial SLAE is given in complex numbers.

In order to use the SLAE solver for real numbers the initial SLAE is transformed into the equivalent real form as a SLAE with double sized dimension. Each pair of real unknowns that form one complex number is treated as a whole block of unknowns , that is equivalent to the complex SLAE as the real block sparse SLAE with small 2 x 2 dense blocks. The parallel FlowVision solver TParFBSS [25,26] is applied for solving the SLAE. The iterative algorithm for solving SLAE in TParFBSS solver consists of several stages. At the first stage Nested Dissection type ordering based on 2x2 block sparsity is computed. This ordering is further used to specify the parallel structure of computations. At the second stage in parallel to the tree structure levels the high order incomplete block triangular factorization of the SLAE matrix is computed. Finally at the third stage the SLAE solution is computed by performing some number of iterations of preconditioned Krylov type algorithm. Heterogeneous parallel implementation of the whole iterative solution algorithm is performed using MPI standard over the distributed memory and using Intel TBB technology over the shared memory.
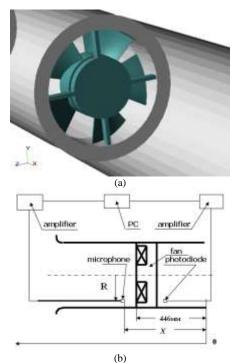
3. Validation Examples

3.1. Fan in the Pipe

(a)

(b)

Fig. 3: Fan installation in the tube (a) and the sketch of pressure pulsation measurements (b)
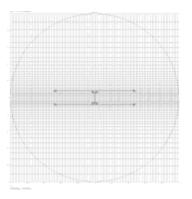

a)

b)

Fig. 4: Mesh and pressure pulsations amplitude in the symmetry plane (a) and in a transverse plane (b)

Comparison the computation versus experiment for the calculation of tonal noise at the first BPF harmonic 222.5 Hz is considered. The tonal noise is generated by the fan VN-2 with a rotor of 60 mm radius. In the computational experiment the fan is installed in the pipe placed in a sphere with non-reflective boundary.
Computational grid in the symmetry plane and at the pipe and the non-reflecting wall of the spherical domain and pressure pulsations amplitude in the symmetry and transverse planes are shown in Fig. 4.
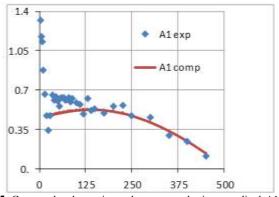

Fig. 5: Computed and experimental pressure pulsations amplitudeA1 (Pa) distribution along the length (mm) of the pipe internal wall at radius r = 73 mm upstream of the fan rotor

Computed and experimental pressure pulsations amplitude distributions along the pipe length internal wall are shown in Fig. 5.

The amplitude of pressure pulsations upstream and downstream the rotor of radius R=60 mm drops sharply in pseudosound zone (x <1.5R ~ 100 mm). Beyond this zone (where there are practically no pseudosound oscillations) the agreement between experimental and calculated data is quite satisfactory.

This task with 250,000 control volumes solved within ~ 1 minute on the 4 core CPU i7-3930K CPU 3.20 GHz.

3.2. Plane Wave Reflection

The plane sound wave in a space filled with moving from the right to the left (against x-direction) medium with averaged Mach number M and limited from the left by plane $x = 0$ on which the acoustic source specified by (5), and on the right by an acoustically perfect reflecting plane $x = L$ is considered.

The wave equation (1) in this case is simplified to the form:

$$\left(1 - M^2\right)\frac{\partial^2 p}{\partial x^2} - 2ikM\frac{\partial p}{\partial x} + k^2 p = 0 \tag{7}$$

With the boundary conditions:

$$\left(J_+\right)_{x=0} = \left(p + \rho c u\right)_{x=0}, \quad \left(u\right)_{x=L} = 0 \tag{8}$$

The analytical solution of the problem (7, 8) can be represented as the sum of satisfying the equation (7) forward and backward waves:

$$p = Ae^{ik_- x} + Be^{-ik_+ x} \tag{9}$$

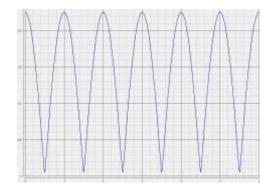where A, B - parameters, that can be found from boundary conditions (8):

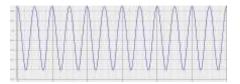$$A = \frac{1}{i}\frac{1}{(k_+ - k) - \frac{k_+}{k_-}(k_- + k)e^{i(k_+ + k_-)L}}, \quad B = \frac{k_+}{k_-}e^{i(k_- + k_-)L}A$$

where $k_- = k/(1-M)$, $k_+ = k/(1+M)$ are wave numbers accounting the medium motion Doppler effect.

In order to analyze the accuracy of the numerical solution of the problem (7, 8) let us consider the case:

$$k = \pi = 3.141592, \quad \left(J_+\right)_{x=0} = (1, 0), \quad L = 6.$$

Numerical solutions for this case for $M = 0$ and $M = 1/\sqrt{2}$ are shown in Fig. 6 as the amplitude of pressure pulsations $|p|$.
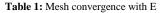

Fig. 6: Pressure $|p|$ as x function. On the top - $M = 0$, on the bottom - $M = 1/\sqrt{2}$

A decrease in the period of the pressure spatial inhomogeneity in 2 times and increase of the minimum pressure module values are due to the Doppler effect for both forward and backward waves.

Table 1 shows the influence of grid density on the accuracy of the numerical solution, described by the relative difference in the L1 norm between calculation and analytical solutions:

$$E = \frac{\sum_{cells}\left|p_{comp} - p_{theory}\right|}{\sum_{cells}\left|p_{theory}\right|}\cdot 100\%$$

Table 1: Mesh convergence with E

$M = 0$

Cells	Number of cells per 1/2 period	E %
100	8	0.2
200	16	0.03
400	32	0.004

$M = 1/\sqrt{2}$

Cells	Number of cells per 1/2 period	E %
100	4	13
200	8	1.3
400	16	0.13

There is a very good convergence of the numerical solution to the exact one with increasing mesh density in both cases. However, the accuracy of solution for $M = 1/\sqrt{2}$ and the same mesh density significantly (about in ~ 5 times) lower than the accuracy of solution for $M = 0$. It can be explained by the increasing of equation system complexity due to the convective term in wave equation proportional to the Mach number.

3.3. Simple Silencer

B. J. Tester suggested an expression for the optimal (so-called Cremer) impedance of the infinite circular duct specified at its internal wall. He also included a correction for mean flow effects:

$$Z_{Cr} = \left(0.88 - 0.38i\right)\frac{kr}{\pi(1+M)^2}, \quad r \text{ - duct radius}$$

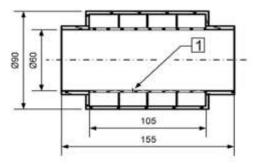and presented appropriate theoretical maximum damping (TL) [27].

Fig. 7: Geometry of silencer studied. Impedance Z_{Cr} is specified at surface marked by 1 (length 105 mm)
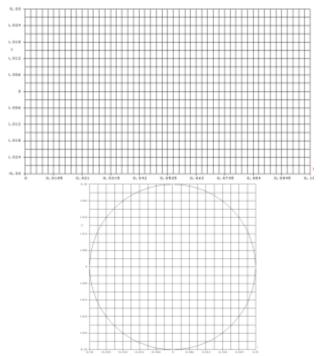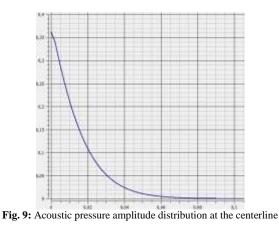
Fig. 8: Computational domain and mesh at the plane of symmetry and at the cross-section

Fig. 9: Acoustic pressure amplitude distribution at the centerline

Below in Table 2 theoretical and computed results are presented.

Table 2: Sound transmission loss (TL=10lgPin/Pout) as a function of frequency

f Hz	TL, dB in Ref. [27]	TL, dB computed
350	81	81.1
700	76	76.3
1050	72	72.7
1400	70	70.6
1750	67.5	67.5
2100	65	66.2
2450	62.5	62.8

One can see that 3-D computations are in a very well agreement with theory in [**Error! Bookmark not defined.**].
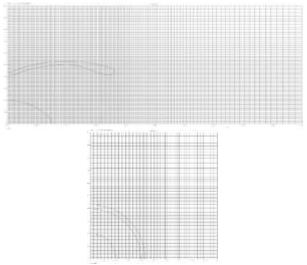
4. Aircraft Engine Model Acoustics

The stationary and disturbed flow in the aircraft engine model inlet part created by the incoming flow with a Mach number equal to 0.3 and the tonal noise at a frequency of 2100 Hz generated by the fan with 16 blades are considered. Model source of the fan disturbance is set analytically in the form of angle periodic with period 360/16 degrees and 1000 Pa amplitude function:

$$J_+ = 1000 \cdot \left[1 + \cos(16\phi)\right].$$ The acoustic analysis is performed

in a case of the presence at the air intake inner wall the SAS with a specific acoustic impedance $Z = 4 - 0.5i$ and in a case of SAS absence. The aim of the calculation is to determine the radiated sound power and sound radiation pattern diagram.

Fig. 10: Grid (140 x 72 x 72) contains 709207 cells. Grid at the plain of symmetry (top) and in the plane in vicinity of fan (bottom)

Computational domain, grid and contours of the model are shown in Fig. 10. A sufficient mesh density inside the air intake ensures restriction of Helmholtz grid number $H < 1$ according [28]. This mesh is used both for the stationary flow and acoustic computations.
Mach number field, included in the equation (1) and the boundary conditions (2-4), is obtained from preliminary computed the stationary axisymmetric turbulent flow. Mach number field in the symmetry plane is shown in Fig. 11. There is shown a significant heterogeneity of this field.
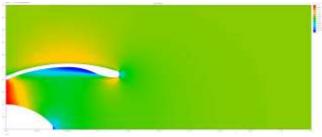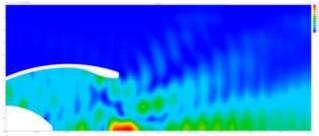

Fig. 11: Mach number in the plane of symmetry (scale ranges $0 - 0.5$)

The results of the acoustic calculation for both cases with and without SAS are shown in **Fig. 12** and **Fig. 13**. It can be seen a significant reduction in acoustic radiation in the case with SAS presence.
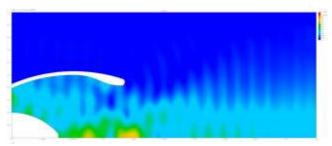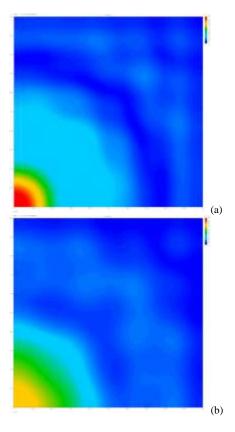
Fig. 12: Amplitude of pressure pulsations in the symmetry plane (scale range 0-1200 Pa). Top - without SAS, bottom - with SAS
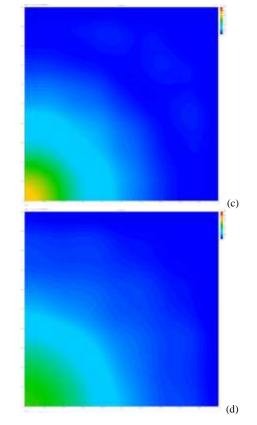
Table 3 shows a total radiated acoustic energy and the effect of the SAS application. Reduction of emitted noise in terms of sound power comprises more than 6 dB.

Table 3: Result of SAS application

	Without SAS	With SAS Z=4-0.5i
Total radiated acoustic energy	*24.1 W*	*5.73 W*
Noise reduction	-	6.25 dB

The calculations were performed on a processor i7 3.2 GHz CPU. Processor time for solving stationary problem takes around 16 minutes; the acoustic problem takes around 24 minutes. It ensures the applicability and effectiveness of this method in engineering practice where the most important requirement is a high performance: calculations of one case should take minutes of CPU time.

(a)

(b)

(c)

(d)

Fig. 13: Amplitude of pressure pulsations in the cross-sections before air inlet at x=0.7 m (a, c) and x=1.1 m (b, d) (scale range 0-600 Pa). (a, b) - without SAS, (c, d) - with SAS

5. Conclusion

The proposed method of modeling the tonal component acoustic field is very efficient in terms of minimization of computer and human resources and calculation accuracy. It can be used for optimization of impedance characteristics and the SAS location for the turbofan engine BPF noise reduction.

Acknowledgement

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