

Nonparametric Prediction Intervals of generalized order statistics from two independent sequences

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Abstract

This paper, discusses the problem of predicting future a generalized order statistic of an iid sequence sample was drawn from an arbitrary unknown distribution, based on observed also generalized order statistics from the same population. The coverage probabilities of these prediction intervals are exact and free of the parent distribution $F(\cdot)$. Prediction formulas of ordinary order statistics and upper record values are extracted as special cases from the productive results. Finally, numerical computations on several models of ordered random variables are given to illustrate the proposed procedures.

Keywords: Prediction intervals; Generalized order statistics; Coverage probability; Confidence intervals; Two-sample prediction.

1. Introduction

The prediction subject of unobserved data has received a considerable attention in the literatures during the last two decades. Several applications of the prediction problems can be found in medical, engineering, stock market studies. Prediction subject have been categorized generally into two types: one-sample prediction and two-sample prediction. One-sample prediction case is based on a sequence of observations, experimenter seeks to predict the future random variables from the same sequence. In two-sample prediction type, using the available observations of past information sample, experimenter interested in (with some level of confidence) predicting some statistics in a future unobserved sample from the same underlying distribution $F(\cdot)$. The past sample and the future sample are iid. Also, the predictor can be either point or interval. Such an interval is said to be a prediction interval (PIs) for the statistic of interest. Also, the prediction interval can be parametric (if it depends on the distribution parameters) or nonparametric (distribution-free). Often the observed data may not appropriate with certain distribution. Therefore, the results may include some error resulting from the mistakes in determining the suitable distribution. Distribution-free predictive inference is a statistical procedure to learn from data in the absence of prior knowledge and using only few modeling assumptions. The proposed prediction intervals are distribution-free, i.e. the corresponding coverage probabilities are known exactly without any assumption about the parent distribution other than being continuous. An exact expression for the prediction coefficient of these intervals is derived.

Many contexts have taken place in the distribution-free PIs direction using several assumptions [1]-[10]. But all these articles shared in one to one prediction way, i.e. predict a future certain type of

samples based on another one. For the purpose of generalization, Mohie El-Din and Emam [11] discussed the predicting of future generalized order statistics, as well as outer and inner PIs based on ordinary order statistics. For more generalization, this article discusses the predicting of future generalized order statistics based on generalized order statistics. The study was conducted over all assumptions of generalized order statistics (*gOSs*) [12] and [13]. Paper is organized as follows: In section 2, some preliminaries are given. In Section 3, distribution-free PIs for a *gOS* from a future *Y*-sequence of iid random variables, based on also *gOSs* from the *X*-sequence are derived. Section 4, includes numerical computations. Finally, conclusions are given in section 5.

This paper aims to construct nonparametric PIs for future *gOSs* based on *gOSs*, therefore, all the previous researches in the field of nonparametric PIs for future *Y*-sample based on another *X*-sample (which can be obtained as a special model of *gOSs* as table 1 considerations) is a special case of this paper. Some numerical results of *oOSs* and *Krecord* (for some $K \in N$) as special models of *gOSs* case I; and *oOSs*, *nonI*, *Seque*, *Pfief*, *PCOs* with two stages ($m_r = 0$ if $r \neq r_1$, $m_{r_1} = n_1$, $k = v - n_1 - n + 1$, $\gamma_r = v - n_1 - r + 1$ if $r \leq r_1$, $\gamma_r = v - n_1 - r + 1$ if $r > r_1$, see, [12] p.48), *Trunc* and k_nrec as special models of case II.

2. Preliminaries

The concept of *gOSs* was introduced by Kamps [12] and was developed by Kamps and Cramer [13]. This concept was introduced as a unified approach to several models of ordered random variables such as, ordinary order statistics (*oOSs*), order statistics with non-integral sample size (*nonI*), *K*-records model (*Krecord*), upper

record values (*record*), sequential order statistics (*Seque*), Pfeifer’s record model (*Pfeif*), progressively Type-II right-censored order statistics sample (*PCOs*), ordering via truncation (*Trunc*) and k_n -record values (k_n *rec*). Table 1, shows these models as special cases of *gOSs*. Let $n \in \mathbb{N}$, $\tilde{m} = (m_1, \dots, m_{n-1}) \in \mathbb{R}_{n-1}$, if $n \geq 2$ ($\tilde{m} \in \mathbb{R}$, arbitrary if $n = 1$) $k \geq 1$, be given constants such that for all $1 \leq i \leq n-1$, $\gamma_i = k + n - i + M_i > 0$, where $M_i = \sum_{j=i}^{n-1} m_j$. We may classify *gOSs* into the following two cases:

Case I: If $m_1 = m_2 = \dots = m_{n-1} = m$, the probability density function (pdf) of $X_{r,n,m,k}$, as introduced by Kamps [12], can be written as

$$f_{X_{r,n,m,k}}(x) = \frac{c_{r-1}}{(r-1)!} \bar{F}^{\gamma_r-1}(x) f(x) g_m^{r-1}(F(x)), \tag{1}$$

where $c_{r-1} = \prod_{j=1}^r \gamma_j$, $\gamma_j = k + (n-j)(m+1)$, $g_m(z) = h_m(z) - h_m(0)$, $0 < z < 1$, such that

$$h_m(z) = \begin{cases} \frac{-(1-z)^{m+1}}{m+1}, & m \neq -1, \\ -\ln(1-z), & m = -1. \end{cases} \tag{2}$$

The survival function of $X_{r,n,m,k}$, is given by:

$$\bar{F}_{X_{i,n,m,k}}(x) = c_{i-1} (1-F(x))^{\gamma_i} \sum_{v=0}^{i-1} \frac{g_m^v(F(x))}{v! c_{i-v-1}}, 1 \leq i \leq n. \tag{3}$$

Case II: If $\gamma_i \neq \gamma_j$, $i, j = 1, 2, \dots, n-1$ and $i \neq j$, the pdf of $X_{r,n,\tilde{m},k}$ which is given in Eq.(1) as be introduced by Kamps and Cramer [13], is given by:

$$f_{X_{r,n,\tilde{m},k}}(x) = c_{r-1} \prod_{i=1}^r a_i(r) (\bar{F}(x))^{\gamma_i-1} f(x), \tag{4}$$

where $a_i(r) = \prod_{j=1, j \neq i}^r \frac{1}{\gamma_j - \gamma_i}$, $1 \leq r \leq n$ and $\gamma_i = k + n - i + M_i > 0$. And the survival function of $X_{r,n,\tilde{m},k}$, is given by:

$$\bar{F}_{X_{i,n,\tilde{m},k}}(x) = c_{i-1} \sum_{v=1}^i \frac{a_v(i)}{\gamma_v} (1-F(x))^{\gamma_v}. \tag{5}$$

Let c_{i-1} , m , $a_i(r)$ and γ_i denote the past scheme X constants, and c_{r-1}^* , m^* , $a_i^*(r)$ and γ_i^* follow the future unobserved scheme Y. The prediction coefficients ϕ not only depend on subscripts, but also depend on observed sample sizes n and n^* in addition the constants k and k^* , i.e. $\phi(\cdot) = \phi(\cdot, n, k; \cdot, n^*, k^*)$.

Table 1: Some special cases of *gOSs*, with $\lambda_i, \alpha_i \in \mathbb{R}^+$, $1 \leq i \leq n-1$.

Model	m_r	k	γ_r
<i>oOSs</i>	0	1	$n-r+1$
<i>nonI</i>	0	$\alpha-n+1$	$\alpha-r+1$
<i>Krecord</i>	-1	$k \in \mathcal{N}$	k
<i>record</i>	-1	1	1
<i>Seque</i>	$(n-r+1)\alpha_r - (n-r)\alpha_{r+1} - 1$	α_n	$(n-r+1)\alpha_r$
<i>Pfeif</i>	$\lambda_r - \lambda_{r+1} - 1$	λ_n	λ_r
<i>PCOs</i>	$R_r \in \mathcal{N}_0$	$R_m + 1$	$m-r+1 + M_i$
<i>Trunc</i>	$\alpha_r k_r - \alpha_{r+1} k_{r+1} - 1$	$\alpha_n k_n$	$\alpha_r k_r$
k_n <i>rec</i>	$\lambda_r k_r - \lambda_{r+1} k_{r+1} - 1$	$\lambda_n k_n$	$\lambda_r k_r$

Lemma1. Based on X-sample observations, suppose we are interested in obtaining $(1-\alpha)100\%$ distribution-free upper pound PIs for Y_r from a future Y-sample of the form $(-\infty, X_i)$, $0 \leq \alpha \leq 1$, such that, the coverage probability $P(X_i \geq Y_r) = 1-\alpha$. We refer to the interval $(-\infty, X_i)$ as $(1-\alpha)100\%$ PI for Y_r . Upon the non-parametric prediction procedure by assuming that Y_r is continuous random variable. Then, we get

$$\phi(i; r) = P(X_i \geq Y_r) = \int_{-\infty}^{\infty} P(X_i \geq y) f_{Y_r}(y) dy. \tag{6}$$

Distribution-free prediction attempt transforming integration base from the random variable to the survival function, to distribute $\bar{F}(\cdot)$ randomly as standard uniform $(0, 1)$ random variable. Therefore, the sampling distribution doesn’t appear in final results. The coverage probabilities of these PIs intervals are exact and are free of the parent distribution $F(\cdot)$, and depend only on the prefixed subscripts of the samples. Therefor, $\phi(i; r) = 1-\alpha$ represents the prediction coefficient which does not depend on the parameters of the parent distribution F , it depends only on the random variable’s positions (the indices i and r) in addition modeling prefixes. Here, X_i are the upper bounds of the prediction interval for Y_r . Under the assumptions of *lemma1*, assume we are interested in obtaining $(1-\alpha)100\%$ distribution-free two sided PIs for Y_r from a future Y-sample of the form (X_i, X_j) , $1 \leq i < j$, such that, the coverage probability $P(X_i \leq Y_r \leq X_j) = 1-\alpha$. We refer to the interval (X_i, X_j) as $(1-\alpha)100\%$ PI for Y_r . Then, we get

$$\begin{aligned} p(X_i \leq Y_r \leq X_j) &= P(X_j \geq Y_r) - P(X_i \geq Y_r) \\ &= \phi(j; r) - \phi(i; r). \end{aligned} \tag{7}$$

Such that, $p(X_i \leq Y_r \leq X_j) = 1-\alpha$ presents the coverage probability for Y_r . Thus, we have (X_i, X_j) is a prediction interval for Y_r . Here, X_i and X_j are the lower and upper bounds of the prediction interval for Y_r , respectively.

3. PIs for individual *gOSs*

In this section, we obtain one and two-sided distribution-free PIs for a future r^{th} *gOSs* $Y_{r,n^*,\tilde{m}^*,k^*}$, $1 \leq i \leq n^*$ based on the endpoints of observed *gOSs*. Let $Y_{1,n^*,\tilde{m}^*,k^*}, \dots, Y_{n^*,n^*,\tilde{m}^*,k^*}$ be n^* *gOSs* based on the continuous cumulative distribution function (cdf) F with density function (pdf) f from a future Y-sequence of i.i.d. random variables, under assumption $m_1^* = m_2^* = \dots = m_{n^*-1}^* = m^*$, or $\gamma_i^* \neq \gamma_j^*$, $i, j = 1, 2, \dots, n^*-1$ and $i \neq j$, and let $X_{i,n,\tilde{m},k}$ be i^{th} *gOSs* from another observed random sample, under assumption $m_1 = m_2 = \dots = m_{n-1} = m$, or $\gamma_i \neq \gamma_j$, $i, j = 1, 2, \dots, n-1$ and $i \neq j$, and further let the underling distribution of the two samples be the same. We are interested here in obtaining one and two-sided distribution-free PIs for a future r^{th} *gOSs* $Y_{r,n^*,\tilde{m}^*,k^*}$, $1 \leq r \leq n^*$ based on the endpoints of observed *gOSs*. The coverage probabilities of this PIs are exact and do not depend on the sampling distribution.

Theorem1. Let $\{X_{i,n,m,k}, 1 \leq i \leq n\}$ under assumption $m_1 = m_2 = \dots = m_{n-1} = m$, and $\{Y_{r,n^*,m^*,k^*}, 1 \leq r \leq n^*\}$ under assumption $m_1^* = m_2^* = \dots = m_{n^*-1}^* = m^*$, be two independent *gOSs* from continuous cdf F . then $(-\infty, X_{i,n,m,k})$, $1 \leq i \leq n$, is an upper prediction bound for the future Y_{r,n^*,m^*,k^*} , with the corresponding prediction coefficient, being free of F , given by:

$$\phi_1(i, m; r, m^*) = \sum_{v=0}^{i-1} C_v(i; r) \times \begin{cases} \sum_{\lambda=0}^v \frac{b_{\lambda}^v(m) B(r, \frac{\gamma_i + \gamma_r^* + \lambda(m+1)}{m^*+1})}{(m^*+1)^r}, & m \neq -1; m^* \neq -1, \\ \sum_{\lambda=0}^v \frac{(r-1)! b_{\lambda}^v(m)}{(\gamma_i + k^* + \lambda(m+1))^r}, & m \neq -1; m^* = -1, \\ \sum_{\eta=0}^{r-1} \frac{v! b_{\eta}^{r-1}(m^*)}{(k + \gamma_r^* + \eta(m^*+1))^{v+1}}, & m = -1; m^* \neq -1, \\ \frac{(v+r-1)!}{(k+k^*)^{v+r}}, & m = -1; m^* = -1, \end{cases} \tag{8}$$

where $C_v(i; r) = \frac{c_{i-1} c_{r-1}^*}{(r-1)! v! c_{i-v-1}}$, $b_{\lambda}^v(m) = \frac{(-1)^{\lambda} \binom{v}{\lambda}}{(m+1)^v}$ and $B(\cdot, \cdot)$ is a beta constant.

Table 2: Some values of $p(X_{i,20,m,k} \leq Y_{r,n^*,m^*,k^*} \leq X_{j,20,m,k})$ for some i, j and r .

Sample		Y			Y					
X	r	i	j	$Y_{r,25}$	record	2record	3record	4record	5record	
$X_{i:20}$	1	1	6	0.4889	0.1923	0.3276	0.4228	0.4892	0.5351	
			12	0.5000	0.4231	0.6268	0.7219	0.7619	0.7732	
			18	0.5000	0.6538	0.8234	0.8562	0.8482	0.8278	
		3	6	0.1062	0.1154	0.18803	0.2320	0.2566	0.2682	
			18	0.1173	0.5769	0.6838	0.6654	0.6156	0.5609	
			18	0.7593	0.0037	0.0222	0.0574	0.1055	0.1617	
	3	1	6	0.8808	0.0306	0.1441	0.2983	0.4508	0.5812	
			12	0.8827	0.1315	0.4334	0.6783	0.8267	0.9065	
			18	0.5000	0.1310	0.4298	0.6680	0.8060	0.8721	
		6	1	18	0.9886	0.0028	0.0503	0.1835	0.3661	0.5443
			22	0.9889	0.0226	0.2249	0.5212	0.7460	0.8755	
			25	0.9889	0.2096	0.6889	0.9063	0.9734	0.9923	
	5	18	6	0.6371	0.0028	0.0503	0.1832	0.3647	0.5401	
			22	0.6374	0.0226	0.2248	0.5209	0.7447	0.8719	
			25	0.4998	0.0002	0.0167	0.1118	0.2950	0.5007	
		10	10	22	0.4998	0.0002	0.0167	0.1118	0.2950	0.5007
			24	0.5000	0.0027	0.0948	0.3489	0.6156	0.7979	
			25	0.5000	0.0207	0.2692	0.6079	0.8240	0.9259	
	15	24	24	0.0782	0.0027	0.0947	0.3473	0.6063	0.7676	
			25	0.0782	0.0207	0.2691	0.6063	0.8146	0.8957	
25			0.0782	0.0207	0.2691	0.6063	0.8146	0.8957		
25		5	1	4	0.1921	0.3320	0.6097	0.6489	0.6160	0.5674
			8	0.1923	0.7749	0.8496	0.7599	0.6717	0.5980	
			20	0.1923	0.9680	0.8683	0.7627	0.6723	0.5981	
	10	2	20	0.0235	0.8899	0.6488	0.4661	0.3446	0.2632	
		1	4	0.3820	0.0452	0.3051	0.5279	0.6400	0.6804	
			8	0.3846	0.3136	0.8108	0.9035	0.8817	0.8350	
12	0.3846		0.6672	0.9615	0.9420	0.8924	0.8385			
2	18	18	0.3846	0.9380	0.9823	0.9437	0.8926	0.8385		
		18	0.0931	0.9331	0.9244	0.8029	0.6779	0.5693		
		18	0.0170	0.9197	0.8185	0.6093	0.4417	0.3226		
	15	1	8	0.5770	0.0669	0.5378	0.8251	0.9087	0.9141	
			12	0.5770	0.2786	0.8772	0.9712	0.9625	0.9347	
			18	0.5770	0.7017	0.9913	0.9865	0.9648	0.9351	
2	18	18	0.2238	0.7014	0.9799	0.9364	0.8593	0.7728		
		18	0.0661	0.7005	0.9495	0.8361	0.6904	0.5565		
		18	0.6912	0.0002	0.0262	0.1338	0.2850	0.4251		
	20	1	8	0.6912	0.0002	0.0262	0.1338	0.2850	0.4251	
			12	0.7692	0.0748	0.6772	0.9324	0.9758	0.9711	
			18	0.7692	0.3714	0.9613	0.9952	0.9884	0.9739	
2	18	18	0.4451	0.3714	0.9593	0.9794	0.9423	0.8870		
		18	0.2042	0.5000	0.9752	0.9390	0.8455	0.7348		
		18	0.2042	0.5000	0.9752	0.9390	0.8455	0.7348		

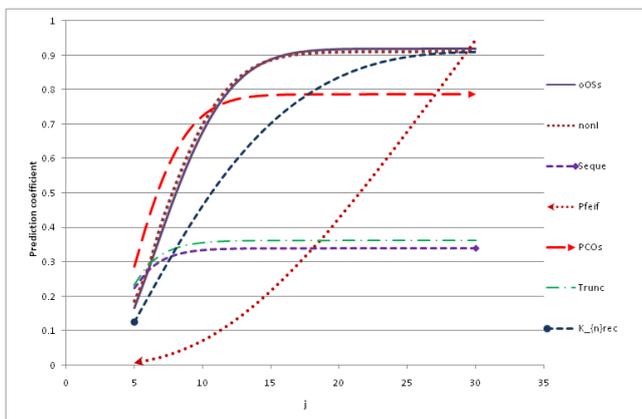


Figure 1: The coverage probabilities of the event $X_{3:30} \leq Y_{5,20,\bar{m}^*,k^*} \leq X_{j:30}$ under table 3 assumptions.

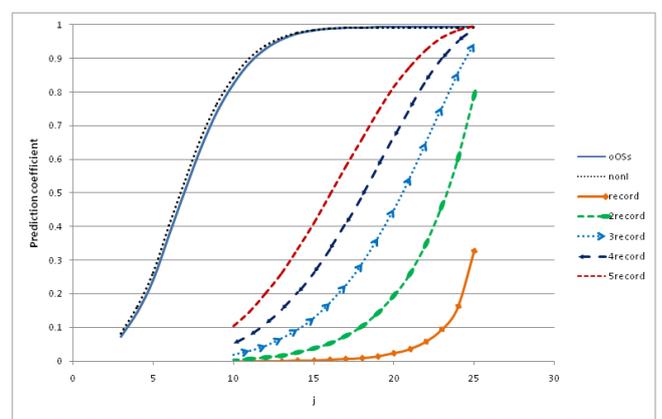


Figure 2: The coverage probabilities of the event $X_{1:25:30} \leq Y_{5,20,\bar{m}^*,k^*} \leq X_{j:25:30}$ under table 4(a) assumptions.

Table 3: Some values of $p(X_{i,n,m,k} \leq Y_{r,20,\widetilde{m}^*,k^*} \leq X_{j,n,m,k})$ for some i, j and r .

Sample X	r	i	j	Y								
				oOSs	nonI	Seque	Pfeif	PCOs	trunc	K_{nrec}		
$X_{i:30}$	1	1	10	0.5971	0.5870	0.5971	0.2903	0.4996	0.6086	0.5845		
			15	0.6000	0.5893	0.6000	0.4516	0.5000	0.6121	0.7595		
			20	0.6000	0.5894	0.6000	0.6129	0.5000	0.6122	0.8567		
		2	10	0.3522	0.3401	0.3522	0.2581	0.2454	0.3662	0.4993		
			3	10	0.2042	0.1937	0.2042	0.2258	0.1183	0.2167	0.4195	
			5	1	10	0.7508	0.7772	0.7921	0.0727	0.9113	0.8039	0.5416
	5	1	15	0.9617	0.9671	0.7971	0.2171	0.9715	0.8102	0.7807		
			20	0.9913	0.9906	0.7973	0.4289	0.9739	0.8103	0.9151		
			3	20	0.9187	0.9088	0.3418	0.4269	0.7881	0.3633	0.8374	
		5	20	0.7512	0.7273	0.1167	0.4196	0.5000	0.1299	0.7106		
			10	1	15	0.5227	0.5796	0.8321	0.1705	0.3544	0.8453	0.7777
				20	0.8902	0.9170	0.8322	0.3839	0.7466	0.8454	0.9159	
	25	0.9944		0.9965	0.8323	0.6518	0.9659	0.8455	0.9759			
	15	5	15	0.5165	0.5712	0.1321	0.1672	0.3510	0.1474	0.5863		
			7	17	0.6705	0.7120	0.0407	0.2352	0.4998	0.0475	0.5117	
			1	20	0.2911	0.3746	0.8502	0.3675	0.0118	0.8642	0.9160	
		5	25	0.7795	0.8458	0.8502	0.6413	0.1109	0.8642	0.9764		
			5	25	0.7794	0.8457	0.1421	0.6392	0.1109	0.1596	0.7880	
			7	27	0.9220	0.9526	0.0439	0.7508	0.2426	0.0517	0.6562	
	20	1	30	0.6000	0.8202	–	0.9386	–	0.0000	0.9911		
5		30	0.6000	0.8202	–	0.9370	–	0.0000	0.8038			
8		30	0.6000	0.8202	–	0.9260	–	0.0000	0.5925			
record	5	1	2	0.2016	0.1949	0.1019	0.2923	0.2016	0.1099	0.2355		
			5	0.2381	0.2283	0.1132	0.6224	0.2381	0.1191	0.3191		
			10	0.2381	0.2283	0.1132	0.6726	0.2381	0.1191	0.3204		
		2	20	0.0365	0.0334	0.0083	0.3819	0.0365	0.0092	0.0845		
			10	1	5	0.4750	0.4557	0.1556	0.6445	0.5286	0.1647	0.3253
				20	0.4762	0.4566	0.1556	0.7009	0.5311	0.1647	0.3267	
	2	20		0.1486	0.1354	0.0146	0.4072	0.1903	0.0163	0.0872		
	15	1		5	0.6985	0.6736	–	0.6518	0.7678	–	0.3267	
		6		0.7101	0.6821	–	0.6806	0.8029	–	0.3278		
		20		0.7143	0.6849	–	0.7099	0.8242	–	0.3281		
	20	2	20	0.3728	0.3362	–	0.4162	0.5408	–	0.0877		
			1	5	0.6532	0.7570	–	0.6554	–	–	0.3273	
10				0.9353	0.9108	–	0.7125	–	–	0.3287		

Proof. Based on lemma1, we can write

$$\begin{aligned} \phi_1(i, m; r, m^*) &= P(X_{i,n,m,k} > Y_{r,n^*,m^*,k^*}) \\ &= \int_{-\infty}^{\infty} P(X_{i,n,m,k} > y) f_{Y_{r,n^*,m^*,k^*}}(y) dy. \end{aligned} \tag{9}$$

Upon substituting the survival function (3) and constructing pdf of Y_{r,n^*,m^*,k^*} from (1), we can express

$$\phi_1(i, m; r, m^*) = \sum_{v=0}^{i-1} C_v(i; r) I_V(i), \tag{10}$$

such that

$$\begin{aligned} I_V(i) &= \int_{-\infty}^{\infty} \overline{F}^{i+\gamma_r-1}(y) g_m^v(F(y)) g_{m^*}^{r-1}(F(y)) f(y) dy \\ &= \int_0^1 y^{i+\gamma_r-1} g_m^v(1-y) g_{m^*}^{r-1}(1-y) dy. \end{aligned} \tag{11}$$

The integration (11) is given for all $m, m^* \in \mathbf{R}$. Thus, based on

assumptions of case I, $I_V(i)$ is given by:

$$\begin{cases} \int_0^1 y^{i+\gamma_r-1} \left(\frac{1-y^{m+1}}{m+1}\right)^v \left(\frac{1-y^{m^*+1}}{m^*+1}\right)^{r-1} dy, & m \neq -1; m^* \neq -1, \\ \int_0^1 y^{i+k^*-1} \left(\frac{1-y^{m+1}}{m+1}\right)^v (-\ln y)^{r-1} dy, & m \neq -1; m^* = -1, \\ \int_0^1 y^{k+\gamma_r-1} (-\ln y)^v \left(\frac{1-y^{m^*+1}}{m^*+1}\right)^{r-1} dy, & m = -1; m^* \neq -1, \\ \int_0^1 y^{k+k^*-1} (-\ln y)^{v+r-1} dy \\ = \int_0^{\infty} z^{v+r-1} e^{-(k+k^*)z} dz = \frac{(v+r-1)!}{(k+k^*)^{v+r}}, & m = -1; m^* = -1. \end{cases} \tag{12}$$

Now, using the binomial expansion on some brackets and solving (12) as the last one, we obtain the required result. Using lemma1 and under assumptions of theorem1, the coverage probability of the event $X_{i,n,m,k} \leq Y_{r,n^*,m^*,k^*} \leq X_{j,n,m,k}$, is given by:

$$p(X_{i,n,m,k} \leq Y_{r,n^*,m^*,k^*} \leq X_{j,n,m,k}) = \phi_1(j, m; r, m^*) - \phi_1(i, m; r, m^*), \tag{13}$$

Table 4(a): Some values of $p(X_{i,30,\tilde{m},k} \leq Y_{r,20,\tilde{m}^*,k^*} \leq X_{j,30,\tilde{m},k})$ based on *PCOs* and *Trunk*, for some i, j and r .

X	r	i	j	Y						
				<i>oOSs</i>	<i>nonI</i>	<i>record</i>	<i>2record</i>	<i>3record</i>	<i>4record</i>	<i>5record</i>
<i>PCOs</i>	1	1	10	0.5984	0.5881	0.3610	0.5834	0.7233	0.8132	0.8719
			20	0.6000	0.5894	0.7604	0.9357	0.9810	0.9939	0.9979
	3	1	10	0.9069	0.9074	0.0139	0.0738	0.1699	0.2814	0.3930
			20	0.7955	0.7885	0.0139	0.0738	0.1699	0.2814	0.3930
	5	1	10	0.8234	0.8443	0.0002	0.0045	0.0201	0.0535	0.1034
			20	0.9926	0.9914	0.0237	0.1957	0.4522	0.6694	0.8135
		3	20	0.9200	0.9096	0.0237	0.1957	0.4522	0.6694	0.8135
			20	0.9200	0.9096	0.0237	0.1957	0.4522	0.6694	0.8135
	7	1	25	0.9992	0.9991	0.1209	0.5634	0.8411	0.9477	0.9831
			25	0.7632	0.7328	0.1209	0.5634	0.8411	0.9477	0.9831
	11	8	23	0.9578	0.9463	0.0002	0.0184	0.1251	0.3244	0.5393
			25	0.9603	0.9477	0.0105	0.1930	0.5115	0.7549	0.8883
	15	1	24	0.9740	0.9854	0.0000	0.0055	0.0616	0.2094	0.4099
			25	0.9946	0.9973	0.0007	0.0480	0.2319	0.4809	0.6906
	19	1	24	0.5700	0.7320	0.0000	0.0004	0.0114	0.0653	0.1823
			25	0.7995	0.8992	0.0000	0.0103	0.0877	0.2560	0.4605
<i>Trunk</i>	5	3	10	0.6604	0.6369	0.1243	0.4907	0.7492	0.8798	0.9413
			10	0.3702	0.3453	0.1244	0.4907	0.7492	0.8798	0.9413
			11	0.3703	0.3453	0.2068	0.6387	0.8585	0.9443	0.9770
	9	2	10	0.9908	0.9900	0.0050	0.1054	0.3256	0.5475	0.7129
			10	0.7850	0.7586	0.0050	0.1054	0.3256	0.5475	0.7129
			12	0.7880	0.7608	0.0335	0.3319	0.6570	0.8417	0.9282
	13	2	14	0.2972	0.2646	0.1328	0.6375	0.8897	0.9669	0.9885
			15	0.9998	0.9997	0.0419	0.4613	0.8058	0.9380	0.9801
			15	0.4443	0.3911	0.0419	0.4613	0.8058	0.9362	0.9741
	19	3	18	0.9993	0.9999	0.0455	0.5649	0.8912	0.9761	0.9946
			18	0.9993	0.9999	0.0455	0.5649	0.8912	0.9761	0.9946
			19	0.9998	0.9999	0.0999	0.7206	0.9515	0.9920	0.9986

where ϕ_1 is given in (8). Thus, we have a prediction interval $(X_{i,n,m,k}, X_{j,n,m,k})$, $1 \leq i < j \leq n$, for Y_{r,n^*,m^*,k^*} ($1 \leq r \leq n^*$), whose prediction coefficient given by (13), is free of F .

Some special cases of ϕ_1 :

We have the following simpler expressions for some special cases one-sided prediction coefficient ϕ_1 that given by (8), and the corresponding two-sided prediction coefficient that given by (13).

- Distribution-free upper pound PIs for Y_{r,n^*} from a future Y-sample of the form $(-\infty, X_{i:n})$, can be obtained as a special case from $\phi_1(i, m; r, m^*)$ by setting $m = m^* = 0, k = k^* = 1, \gamma_i = n - i + 1, 1 \leq i \leq n$ and $\gamma_r^* = n^* - r + 1, 1 \leq r \leq n^*$, and has the following form

$$p(X_{i:n} \geq Y_{r:n^*}) = \phi_1(i, 0; r, 0) = \sum_{v=0}^{i-1} r \binom{n-i+v}{v} \binom{n^*}{r} \sum_{\lambda=0}^v (-1)^\lambda \binom{v}{\lambda} B(r, n-i+n^*-r+2). \tag{14}$$

Distribution-free two sided PIs for Y_{r,n^*} of the form $(X_{i:n}, X_{j:n})$ which was discussed by Mohie El-Din et al [1] appear here as a special case, such that

$$p(X_{i:n} \leq Y_{r:n^*} \leq X_{j:n}) = P(X_{j:n} \geq Y_{r:n^*}) - P(X_{i:n} \geq Y_{r:n^*}). \tag{15}$$

Similarly:

- Prediction interval of future *record* based on *oOSs* which was discussed by Ahmadi and Balakrishnan [5], can be given with Lemma1 by:

$$p(X_{i:n} \geq U_r) = \phi_1(i, 0; r, -1) = \sum_{v=0}^{i-1} \binom{n-i+v}{v} \sum_{\lambda=0}^v \frac{(-1)^\lambda \binom{v}{\lambda}}{(n-i+\lambda+2)^r}. \tag{16}$$

- Prediction interval of future *oOSs* based on *record* which was discussed by Ahmadi and Balakrishnan [5], is given by:

$$p(U_i \leq Y_{r:n^*} \leq U_j) = \phi_1(j, -1; r, 0) - \phi_1(i, -1; r, 0) = \sum_{v=i}^{j-1} r \binom{n^*}{r} \sum_{\lambda=0}^{r-1} \frac{(-1)^\lambda \binom{r-1}{\lambda}}{(n^*-r+\lambda+2)^{v+1}}. \tag{17}$$

- Prediction interval of future *record* based on *record* also, which was discussed by Raqab and Balakrishnan [8], is given by:

$$p(U_i \leq U_r^* \leq U_j) = \phi_1(j, -1; r, -1) - \phi_1(i, -1; r, -1) = \sum_{v=i}^{j-1} \binom{v+r-1}{v} \frac{1}{2^{v+r}}. \tag{18}$$

Table 4(b): Some values of $p(X_{i,30,\tilde{m},k} \leq Y_{r,20,\tilde{m}^*,k^*} \leq X_{j,30,\tilde{m},k})$ based on *Seque* and *Pfief*, for some i, j and r .

X	r	i	j	Y						
				$Y_{r:20}$	<i>nonI</i>	<i>record</i>	<i>2record</i>	<i>3record</i>	<i>4record</i>	<i>5record</i>
<i>Seque</i>	1	1	5	0.7205	0.7151	0.2335	0.4027	0.5278	0.7220	0.6940
			7	0.7478	0.7398	0.4027	0.6271	0.7585	0.8387	0.8894
			9	0.7499	0.7416	0.5776	0.8036	0.9016	0.9477	0.9708
	2	2	5	0.4143	0.4045	0.2335	0.4027	0.5279	0.6221	0.6941
			7	0.4417	0.4292	0.4027	0.6271	0.7585	0.8387	0.8894
			9	0.9280	0.9255	0.1090	0.2902	0.4555	0.5872	0.6873
	3	3	11	0.9392	0.9351	0.2356	0.5186	0.7071	0.8211	0.8889
			11	0.9398	0.9356	0.4066	0.7315	0.8791	0.9435	0.9723
			11	0.4765	0.4584	0.4066	0.7315	0.8791	0.9435	0.9723
	4	4	1	0.9883	0.9895	0.0218	0.1358	0.3038	0.4687	0.6058
			13	0.9969	0.9964	0.1786	0.5654	0.8027	0.9126	0.9606
			13	0.8294	0.8144	0.0721	0.3241	0.5720	0.7432	0.8481
	11	5	16	0.9713	0.9632	0.0054	0.1521	0.4603	0.7146	0.8612
			19	0.9716	0.9634	0.0589	0.5197	0.8466	0.9570	0.9880
			20	0.9491	0.9252	0.0093	0.2879	0.6933	0.8961	0.9672
	20	10	22	0.7381	0.6668	0.0550	0.5910	0.9048	0.9809	0.9961
22			0.9159	0.8409	0.0102	0.3469	0.7688	0.9364	0.9799	
22			0.9159	0.8409	0.0102	0.3469	0.7688	0.9364	0.9799	
<i>Pfeif</i>	5	1	10	0.2381	0.2283	0.2002	0.6024	0.8250	0.9228	0.9647
			15	0.2381	0.2283	0.2558	0.6968	0.8939	0.9629	0.9865
	7	2	15	0.0649	0.0598	0.2558	0.6968	0.8939	0.9629	0.9865
			10	0.3331	0.3194	0.0629	0.3633	0.6435	0.8121	0.9015
	9	5	10	0.0084	0.0069	0.0629	0.3633	0.6435	0.8121	0.9015
			10	0.4271	0.4099	0.0176	0.1956	0.4576	0.6678	0.8039
	11	7	11	0.0064	0.0050	0.0192	0.2096	0.4825	0.6940	0.8260
			11	0.5196	0.4994	0.0051	0.1058	0.3235	0.5443	0.7111
	13	5	17	0.0560	0.0463	0.0076	0.1496	0.4248	0.6665	0.8214
			20	0.6174	0.5927	0.0023	0.0851	0.3154	0.5682	0.7548
	15	30	20	0.6188	0.5935	0.0034	0.1181	0.4052	0.6775	0.8466
			20	0.2088	0.1750	0.0060	0.0408	0.2025	0.4327	0.6393
	17	25	30	0.2141	0.1782	0.0007	0.0498	0.2388	0.4916	0.7014
			30	0.7885	0.7668	0.0002	0.0277	0.1729	0.4111	0.6370
	19	8	30	0.2156	0.1674	0.0002	0.0277	0.1729	0.4111	0.6370
			30	0.7497	0.7979	0.0001	0.0128	0.1061	0.3003	0.5223
8	30	30	0.3475	0.3060	0.0001	0.0128	0.1061	0.3003	0.5223	

• Prediction interval of future *gOSs* case I based on *oOSs*, is given by:

$$p(X_{i:n} \geq Y_{r:n^*,m^*,k^*}) = \sum_{v=0}^{i-1} \frac{\binom{n-i+v}{v} c_{r-1}}{(r-1)!} \sum_{\lambda=0}^v (-1)^\lambda \binom{v}{\lambda} \begin{cases} \frac{B(r, \frac{n-i+1+\gamma_r^*+\lambda}{m^*+1})}{(m^*+1)^r}, & m^* \neq -1, \\ \frac{(r-1)!}{(n-i+1+k^*+\lambda)^r}, & m^* = -1. \end{cases} \tag{19}$$

• Prediction interval of future *gOSs* case I based on *record*, is given by:

$$p(U_i \geq Y_{r:n^*,m^*,k^*}) = \sum_{v=0}^{i-1} \frac{1}{(r-1)!v!} \begin{cases} c_{r-1}^* \sum_{\eta=0}^{r-1} \frac{v! b_{\eta}^{r-1}(m^*)}{(\gamma_r^* + \eta(m^*+1))^{v+1}}, & m^* \neq -1, \\ \frac{(v+r-1)!(k^*)^r}{(k^*+1)^{v+r}}, & m^* = -1. \end{cases} \tag{20}$$

• Prediction interval of future *oOSs* based on *gOSs* case I, is given by:

$$p(X_{i:n,m,k} \geq Y_{r:n^*}) = \sum_{v=0}^{i-1} \frac{n^*!}{(n^*-r)!(r-1)!v!} \begin{cases} \frac{c_{i-1}}{c_{i-v-1}} \sum_{\lambda=0}^v b_{\lambda}^v(m) B(r, \gamma_i + n^* - r + 1 + \lambda(m+1)), & m \neq -1, \\ k^v \sum_{\eta=0}^{r-1} \frac{v!(-1)^\eta \binom{r-1}{\eta}}{(k+n^*-r+1+\eta)^{v+1}}, & m = -1. \end{cases} \tag{21}$$

• Prediction interval of future *record* based on *gOSs* case I, given by:

$$p(X_{i:n,m,k} \geq U_r^*) = \sum_{v=0}^{i-1} \frac{1}{(r-1)!v!} \begin{cases} \frac{c_{i-1}}{c_{i-v-1}} \sum_{\lambda=0}^v \frac{(r-1)! b_{\lambda}^v(m)}{(\gamma_i+1+\lambda(m+1))^r}, & m \neq -1, \\ \frac{(v+r-1)!k^v}{(k+1)^{v+r}}, & m = -1. \end{cases} \tag{22}$$

Theorem2. Let $\{X_{i,n,m,k}, 1 \leq i \leq n\}$ under assumption $m_1 = m_2 = \dots = m_{n-1} = m$, and $\{Y_{r,n^*,\tilde{m}^*,k^*}, 1 \leq r \leq n^*\}$ under assumption $\gamma_i \neq \gamma_j$, $i, j = 1, 2, \dots, n^* - 1$ and $i \neq j$, be two independent *gOSs* from continuous cdf F . then $(-\infty, X_{i,n,m,k}), 1 \leq i \leq n$, is distribution-free one-sided

Table 5: Some values of $p(X_{i,30,\tilde{m},k} \leq Y_{r,20,\tilde{m}^*,k^*} \leq X_{j,30,\tilde{m},k})$ for some i, j and r .

X	r	i	j	Y							
				<i>oOSs</i>	<i>nonI</i>	<i>Seque</i>	<i>Pfeif</i>	<i>PCOs</i>	<i>trunc</i>	<i>K_nrec</i>	
<i>Seque</i>	1	1	10	0.6000	0.6012	0.6000	0.8347	0.5000	0.6122	0.9021	
			30	0.6000	0.6012	0.6000	0.9677	0.5000	0.6122	0.9091	
	5	1	10	0.2522	0.2534	0.2522	0.7723	0.1629	0.2650	0.7462	
			2	0.9926	0.9927	0.7973	0.7803	0.9739	0.8103	0.9779	
		2	10	0.9070	0.9081	0.3931	0.7771	0.7850	0.4169	0.8962	
	10	1	10	0.6769	0.6795	0.1358	0.7598	0.4573	0.1379	0.7274	
			3	0.9921	0.9918	0.8323	0.7611	0.9740	0.8455	0.9806	
		2	12	0.9713	0.9974	0.4346	0.9035	0.9966	0.4565	0.9150	
	15	3	12	0.9710	0.9717	0.1523	0.8939	0.9812	0.1662	0.7501	
			4	0.9922	0.9986	0.0429	0.9612	0.9986	0.0490	0.5466	
		30	0.9922	0.9986	0.0429	0.9614	0.9998	0.0490	0.5466		
	20	6	30	0.8554	0.8598	0.0016	0.7801	0.9917	0.0019	0.2075	
			1	0.8678	0.8437	–	0.9835	0.0000	0.0000	0.9913	
		4	0.9979	0.9967	–	0.9643	0.0000	0.0000	0.5478		
	<i>Pfeif</i>	2	1	10	0.8235	0.8242	0.7013	0.1792	0.7435	0.7137	0.5860
				15	0.8380	0.8388	0.7045	0.3542	0.7457	0.7177	0.7980
2			15	0.6386	0.6402	0.4419	0.3464	0.4870	0.4600	0.7441	
6		1	10	0.6470	0.6697	0.7951	0.0696	0.7781	0.8074	0.5565	
			3	0.9488	0.8201	0.3383	0.3480	0.9099	0.3602	0.8058	
		4	29	0.9139	0.9119	0.1984	0.9390	0.8349	0.2163	0.8467	
12		1	18	0.5800	0.5623	0.8321	0.3089	0.2581	0.8458	0.8852	
			3	0.5799	0.5502	0.3737	0.3085	0.2581	0.3988	0.8124	
		6	24	0.9604	0.9204	0.0697	0.6289	0.6289	0.7679	0.7007	
18		1	25	0.3914	0.3321	–	0.6870	0.0000	0.8711	0.9803	
			26	0.5265	0.3223	–	0.7487	0.0000	0.8711	0.9847	
		27	0.6755	0.3001	–	0.8111	0.0000	0.8711	0.9875		
<i>PCOs</i>		3	1	10	0.8757	0.8763	0.6447	0.1495	0.8757	0.4546	0.6177
				20	0.8813	0.8819	0.6450	0.6433	0.8814	0.6549	0.9560
			2	20	0.6940	0.6953	0.3510	0.6409	0.6940	0.3628	0.9171
	6	4	20	0.6920	0.6917	0.0981	0.0865	0.6982	0.1052	0.4708	
			6	0.4708	0.4681	0.0186	0.5812	0.5000	0.0207	0.6755	
		12	3	15	0.9059	0.9001	0.2210	0.2564	0.8101	0.2328	0.7844
	16	20	0.9958	0.9732	0.2210	0.5660	0.9913	0.2328	0.8958		
			1	16	0.7422	0.7222	0.7315	0.3009	0.5000	0.7423	0.8842
		20	0.9746	0.9521	0.7315	0.5584	0.8958	0.7423	0.9640		
	18	2	20	0.9745	0.9517	0.4330	0.5583	0.8958	0.4477	0.9391	
			2	0.9291	0.8880	0.4372	0.5556	0.7429	0.4522	0.9393	
		8	22	0.9778	0.9231	0.0031	0.6799	0.9158	0.0037	0.5356	

PI for the future $Y_{r,n^*,\tilde{m}^*,k^*}$, with the corresponding prediction coefficient $\phi_2(i, m; r, \tilde{m}^*)$, that does not depend on the sampling distribution F , and is given by:

$$\sum_{v=0}^{i-1} (r-1)! C_v(i; r) \sum_{\mu=1}^r a_{\mu}^*(r) \begin{cases} \frac{B(v+1, \frac{\gamma_i + \gamma_{\mu}^*}{m+1})}{(m+1)^{v+1}}, & m \neq -1, \\ \frac{v!}{(k + \gamma_{\mu}^*)^{v+1}}, & m = -1. \end{cases} \tag{23}$$

Proof. Under the assumption that $\{Y_{r,n^*,\tilde{m}^*,k^*}, 1 \leq r \leq n^*\}$ are continuous r.v.'s, we can write

$$\begin{aligned} \phi_2(i, m; r, \tilde{m}^*) &= P(X_{i,n,m,k} > Y_{r,n^*,\tilde{m}^*,k^*}) \\ &= \int_{-\infty}^{\infty} P(X_{i,n,m,k} > y) f_{Y_{r,n^*,\tilde{m}^*,k^*}}(y) dy. \end{aligned} \tag{24}$$

Using (3) and (4), ϕ_2 can be written as

$$\phi_2(i, m; r, \tilde{m}^*) = \sum_{v=0}^{i-1} \frac{c_{i-1} c_{r-1}^*}{v! c_{i-v-1}} \sum_{\mu=1}^r a_{\mu}^*(r) J_{v,\mu}(i), \tag{25}$$

such that

$$J_{v,\mu}(i) = \int_{-\infty}^{\infty} \bar{F}^{\gamma_i + \gamma_{\mu}^* - 1}(y) g_m^v(F(y)) f(y) dy. \tag{26}$$

Thus, based on $g_m(\cdot)$ and (2), $J_{v,\mu}(i)$ is given by:

$$J_{v,\mu}(i) = \begin{cases} \int_{-\infty}^{\infty} \bar{F}^{\gamma+\gamma_{\mu}^*-1}(y) \left(\frac{1-\bar{F}^{m+1}(y)}{m+1}\right)^{\nu} f(y)dy, & m \neq -1, \\ \int_{-\infty}^{\infty} \bar{F}^{k+\gamma_{\mu}^*-1}(y) (-\ln \bar{F}(y))^{\nu} f(y)dy, & m = -1. \end{cases} \tag{27}$$

Using the following transformation $\bar{F}(y) = u$, we get

$$J_{v,\mu}(i) = \begin{cases} \int_0^1 u^{\gamma+\gamma_{\mu}^*-1} \left(\frac{1-u^{m+1}}{m+1}\right)^{\nu} du, & m \neq -1, \\ \int_0^1 u^{k+\gamma_{\mu}^*-1} (-\ln u)^{\nu} du, & m = -1. \end{cases} \tag{28}$$

The prediction coefficient $\phi_2(i, m; r, \tilde{m}^*)$, given in (23) is obtained directly by solving (28).

Some special cases of ϕ_2 :

- Prediction interval of future *oOSs* based on also *oOSs*, is given by:

$$P(X_{i:n} \geq Y_{r:n^*}) = \phi_2(i, 0; r, \tilde{0}) = \sum_{v=0}^{i-1} r! \binom{n-i+v}{v} \binom{n^*}{r} \sum_{\mu=1}^r a_{\mu}^*(r) B(v+1, n-i+n^*-\mu+2). \tag{29}$$

- Prediction interval of future *oOSs* based on *record*, is given by:

$$P(U_i \geq Y_{r:n^*}) = \phi_2(i, -1; r, \tilde{0}) = \sum_{v=0}^{i-1} r! \binom{n^*}{r} \sum_{\mu=1}^r \frac{a_{\mu}^*(r)}{(n^*-\mu+2)^{v+1}}. \tag{30}$$

- Prediction interval of future *gOSs* case II based on *oOSs* which was discussed by Mohie El-Din and Emam [11], is given by:

$$P(X_{i:n} \geq Y_{r,n^*,\tilde{m}^*,k^*}) = \phi_2(i, 0; r, \tilde{m}^*) = \sum_{v=0}^{i-1} \frac{\binom{n-i+v}{v} c_{r-1}^*}{(r-1)!} \sum_{\mu=1}^r a_{\mu}^*(r) B(v+1, n-i+1+\gamma_{\mu}^*). \tag{31}$$

- Prediction interval of future *oOSs* based on *gOSs* case I which was discussed in [11], is given by:

$$P(X_{i,n,m,k} > Y_{r:n^*}) = \phi_2(i, m; r, \tilde{0}) = \sum_{v=0}^{i-1} \frac{r \binom{n^*}{r}}{v!} \sum_{\mu=1}^r a_{\mu}^*(r) \begin{cases} \frac{c_{i-1} B(v+1, \frac{\gamma+n^*-\mu+1}{m+1})}{c_{i-v-1} (m+1)^{v+1}}, & m \neq -1, \\ \frac{v! k^v}{(k+n^*-\mu+1)^{v+1}}, & m = -1. \end{cases} \tag{32}$$

- Prediction interval of future *gOSs* case II based on *record*, is given by:

$$P(U_i \geq Y_{r,n^*,\tilde{m}^*,k^*}) = \phi_2(i, -1; r, \tilde{m}^*) = \sum_{v=0}^{i-1} \frac{c_{r-1}^*}{(r-1)! v!} \sum_{\mu=1}^r a_{\mu}^*(r) \frac{v!}{(\gamma_{\mu}^*+1)^{v+1}}. \tag{33}$$

Under the assumption of lemma1, $(X_{i,n,m,k}, X_{j,n,m,k}), 1 \leq i < j \leq n$, is a distribution-free PIs for $Y_{r,n^*,\tilde{m}^*,k^*} (1 \leq r \leq n^*)$, whose coverage probability is free of the parent distribution F , given by:

$$P(X_{i,n,m,k} \leq Y_{r,n^*,\tilde{m}^*,k^*} \leq X_{j,n,m,k}) = \phi_2(j, m; r, \tilde{m}^*) - \phi_2(i, m; r, \tilde{m}^*), \tag{34}$$

where ϕ_2 is given in (23).

Proof. By assumption that $\{Y_{r,n^*,\tilde{m}^*,k^*}, 1 \leq r \leq n^*\}$ are continuous r.v.'s, we have By using (5) and constructing the pdf of $Y_{r,n^*,\tilde{m}^*,k^*}$ from (1), ϕ_3 take the form

$$\begin{aligned} \phi_3(i, \tilde{m}; r, m^*) &= C(i; r) \sum_{v=1}^i \frac{a_v(i)}{\gamma_v} \zeta_v(i), \tag{37} \\ \phi_3(i, \tilde{m}; r, m^*) &= P(X_{i,n,\tilde{m},k} > Y_{r,n^*,m^*,k^*}) \\ &= \int_{-\infty}^{\infty} P(X_{i,n,\tilde{m},k} > y) f_{Y_{r,n^*,m^*,k^*}}(y) dy. \tag{36} \end{aligned} \quad \text{where}$$

$$\zeta_v(i) = \begin{cases} \int_{-\infty}^{\infty} (\bar{F}(y))^{\gamma_v+\gamma_{\mu}^*-1} \left(\frac{1-\bar{F}^{m^*+1}(y)}{m^*+1}\right)^{r-1} f(y)dy, & m^* \neq -1, \\ \int_{-\infty}^{\infty} (\bar{F}(y))^{\gamma_v+k^*-1} (-\ln(\bar{F}(y)))^{r-1} f(y)dy, & m^* = -1. \end{cases} \tag{38}$$

Making the transformation $\bar{F}(y) = u$, we get

$$\zeta_{\nu}(i) = \begin{cases} \int_0^1 u^{\gamma_{\nu} + \gamma_r - 1} \left(\frac{1-u^{m^*+1}}{m^*+1} \right)^{r-1} du, & m^* \neq -1, \\ \int_0^1 u^{\gamma_{\nu} + k^* - 1} (-\ln(u))^{r-1} du, & m^* = -1. \end{cases} \quad (39)$$

By solving the integrations (39), easily we obtain the required result.

Some special cases of ϕ_3 :

- Prediction coefficient of future *oOSs* based on also *oOSs*, is given by:

$$\phi_3(i, \tilde{0}; r, 0) = r(i!) \binom{n}{i} \binom{n^*}{r} \sum_{\nu=1}^i \frac{(-1)^{i-\nu} B(r, n-i+n^*-r+2)}{(\nu-1)!(i-\nu)!(n-\nu+1)}. \quad (40)$$

- Prediction coefficient of future *record* based on *oOSs*, is given by:

$$\phi_3(i, \tilde{0}; r, -1) = \binom{n}{i} \sum_{\nu=1}^i \frac{(-1)^{i-\nu} \nu \binom{i}{\nu}}{(n-\nu+1)(n-\nu+2)^r}. \quad (41)$$

- Prediction coefficient of future *gOSs* case I based on *oOSs*, is given by:

$$\phi_3(i, \tilde{0}; r, m^*) = \frac{n!}{(n-i)!(r-1)!} \sum_{\nu=1}^i \frac{a_{\nu}(i)}{n-\nu+1} \begin{cases} \frac{B(r, \frac{n-\nu+1+\gamma_r^* c_{r-1}^*}{m^*+1})}{(m^*+1)^r}, & m^* \neq -1, \\ \frac{(r-1)!}{(\frac{n-\nu+1}{k^*}+1)^r}, & m^* = -1. \end{cases} \quad (42)$$

- Prediction coefficient of future *oOSs* based on *gOSs* case II, is given by:

$$\phi_3(i, \tilde{m}; r, 0) = r \binom{n^*}{r} c_{i-1} \sum_{\nu=1}^i \frac{a_{\nu}(i)}{\gamma_{\nu}} B(r, \gamma_{\nu} + n^* - r + 1). \quad (43)$$

- Prediction coefficient of future *record* based on *gOSs* case II, is given by:

$$\phi_3(i, \tilde{m}; r, -1) = \frac{c_{i-1}}{(r-1)!} \sum_{\nu=1}^i \frac{a_{\nu}(i)}{\gamma_{\nu}} \frac{(r-1)!}{(\gamma_{\nu}+1)^r}. \quad (44)$$

Under assumptions of *theorem3*, then $(X_{i,n,\tilde{m},k}, X_{j,n,\tilde{m},k})$, $1 \leq i < j \leq n$, is a distribution-free PIs for Y_{r,n^*,m^*,k^*} ($1 \leq r \leq n^*$), whose coverage probability is free of the parent distribution F , is given by:

$$p(X_{i,n,\tilde{m},k} \leq Y_{r,n^*,m^*,k^*} \leq X_{j,n,\tilde{m},k}) = \phi_3(j, \tilde{m}; r, m^*) - \phi_3(i, \tilde{m}; r, m^*). \quad (45)$$

where ϕ_3 is given in (??).

Theorem4. Let $\{X_{i,n,\tilde{m},k}, 1 \leq i \leq n\}$ under assumption $\gamma_i \neq \gamma_j$, $i, j = 1, 2, \dots, n - 1$ and $i \neq j$ and $\{Y_{r,n^*,\tilde{m}^*,k^*}, 1 \leq r \leq n^*\}$ under assumption $\gamma_r^* \neq \gamma_j^*$, $i, j = 1, 2, \dots, n^* - 1$ and $i \neq j$ be two independent *gOSs* from continuous cdf F . then $(-\infty, X_{i,n,\tilde{m},k}), 1 \leq i \leq n$, is distribution-free one-sided PI for the future $Y_{r,n^*,\tilde{m}^*,k^*}$, with the corresponding prediction coefficient $\phi_4(i, \mu; r)$, that does not depend on the sampling distribution F , and is given by:

$$\phi_4(i, \tilde{m}; r, \tilde{m}^*) = c_{i-1} c_{r-1}^* \sum_{v=1}^i \frac{a_v(i)}{\gamma_v} \sum_{\mu=1}^r \frac{a_\mu^*(r)}{\gamma_v + \gamma_\mu^*}. \tag{46}$$

$$\begin{aligned} \phi_4(i, \tilde{m}; r, \tilde{m}^*) &= \int_{-\infty}^{\infty} c_{i-1} \sum_{v=1}^i \frac{a_v(i)}{\gamma_v} (1 - F(y))^{\gamma_v} c_{r-1}^* f(y) \sum_{\mu=1}^r a_\mu^*(r) (1 - F(y))^{\gamma_\mu^* - 1} dy \\ &= c_{i-1} \sum_{v=1}^i \frac{a_v(i)}{\gamma_v} c_{r-1}^* \sum_{\mu=1}^r a_\mu^*(r) \int_{-\infty}^{\infty} (1 - F(y))^{\gamma_v + \gamma_\mu^* - 1} f(y) dy. \end{aligned} \tag{48}$$

Using the transformation $\bar{F}(y) = u$, and solving the integration, easily we obtain the required result. Based on ϕ_4 that given in (46) and under *theorem4* assumptions, then $(X_{i,n,\tilde{m},k}, X_{j,n,\tilde{m},k}), 1 \leq i < j \leq n$, is a distribution-free PIs for $Y_{r,n^*,\tilde{m}^*,k^*} (1 \leq r \leq n^*)$, whose coverage probability is free of the parent distribution F , given by:

$$p(X_{i,n,\tilde{m},k} \leq Y_{r,n^*,\tilde{m}^*,k^*} \leq X_{j,n,\tilde{m},k}) = \phi_4(j, \tilde{m}; r, \tilde{m}^*) - \phi_4(i, \tilde{m}; r, \tilde{m}^*), \tag{49}$$

4. Numerical Results

In section 3, distribution-free PIs for future *gOSs* based on also *gOSs* is constructed. To illustrate the productive prediction coefficient for some choices of i, j and r , and by using some different choices of γ_i and γ_r^* in table 1 to gaining the special schemes of the *gOSs*. Table 2 presents some values of the coverage probability $p(X_{i,20,m,k} \leq Y_{r,n^*,m^*,k^*} \leq X_{j,20,m,k})$ of future, *oOSs* (by setting $\gamma_r^* = n^* - r + 1$) with $n^* = 25$ and *Krecord* (by setting $\gamma_r^* = K$) with $K = 1, 2, 3, 4$ and 5 , based on *oOSs* and *record* consecutively, such that $p(X_{i,n,m,k} \leq Y_{r,n^*,m^*,k^*} \leq X_{j,n,m,k})$ does not depend on the parent distribution F , given by (13). Some values of the coverage probability $p(X_{i,n,m,k} \leq Y_{r,20,\tilde{m}^*,k^*} \leq X_{j,n,m,k})$ of future *oOSs*, *nonI* (by setting $\gamma_r = (n^* + 0.9) - r + 1$), *Seque* (using $\alpha_r = r^2$), *Pfeif* (by setting $\gamma_r = r^2$), *PCOs* (using $r_1 = 5, n_1 = 5$), *Trunc* (using $\alpha_r = r^2, k_r = n^* - r$) and *K_nrec* (using $\beta_r = r^2, k_r = r + 2$), based on *oOSs* with $n = 30$ and *record* are presented respectively, in table 3, with the coverage probability that given by (34).

Table 4(a) presents some values of $p(X_{i,30,\tilde{m},k} \leq Y_{r,n^*,m^*,k^*} \leq X_{j,30,\tilde{m},k})$ of future *oOSs* and *Krecord*, $K = 1, 2, 3, 4$ and 5 based on *PCOs* (using $r_1 = 5, n_1 = 5$) and *Trunc* (using $\alpha_r = r^{-1}, k_r = n^* - r$), respectively. Under the same assumption, table 4(b) holds based on *Seque* (using $\alpha_r = 2r^{-1}$) and *Pfeif* (by setting $\gamma_r = r^2$), respectively. Table 5 presents some values of $p(X_{i,30,\tilde{m},k} \leq Y_{r,20,\tilde{m}^*,k^*} \leq X_{j,30,\tilde{m},k})$ based on *Seque* (using $\alpha_r = r^{-1}$), *Pfeif* (by setting $\gamma_r = n - r$) and *PCOs* (using $r_1 = 5, n_1 = 5$), respectively, the prediction coefficient of future *oOSs*, *nonI* (using $\alpha_r = (n^* - 0.1) - r + 1$), *Seque* (using $\alpha_r = r^2$), *Pfeif* (by setting $\gamma_r = r^2$), *PCOs* (using $r_1 = 5, n_1 = 5$), *Trunc* (using $\alpha_r = r^2, k_r = n^* - r$) and *K_nrec* (using $\beta_r = r^2, k_r = r + 2$), respectively.

Proof. Using assumptions, we found that

$$\begin{aligned} \phi_4(i, \tilde{m}; r, \tilde{m}^*) &= P(X_{i,n,\tilde{m},k} > Y_{r,n^*,\tilde{m}^*,k^*}) \\ &= \int_{-\infty}^{\infty} P(X_{i,n,\tilde{m},k} > y) f_{Y_{r,n^*,\tilde{m}^*,k^*}}(y) dy. \end{aligned} \tag{47}$$

Using (4) and (5), ϕ_4 has the following form

Under table 3 assumptions, figure 1 plots $p(X_{3,30,0,1} \leq Y_{5,20,\tilde{m}^*,k^*} \leq X_{j,30,0,1})$, which presents the coverage probability of future 5th *gOSs* case II based on *oOSs*. Therefore, $(X_{3:30}, X_{j:30}), 1 \leq j \leq 30$, is a distribution-free PIs for $Y_{5,20,\tilde{m}^*,k^*}$. Under table 4(a) assumptions, figure 2 plots the coverage probability of future 5th *gOSs* case I based on *PCOs*. Then, $(X_{1:25:30}, X_{j:25:30}), 1 \leq j \leq 30$, is a distribution-free PIs for $Y_{5,20,m^*,k^*}$.

5. Conclusions

The prediction of unobserved statistics arises naturally in several real life situations. In This paper, nonparametric PIs for some statistics in a future unobserved *gOSs* based on *gOSs* from the same underlying distribution $F(\cdot)$ are constructed. The proposed procedure can be extended to construct the outer and inner prediction intervals for future *gOSs* based on *gOSs*. The following conclusions are noted here:

- The prediction coefficient are decreasing with i and increasing with j , as it was expected.
- All prediction coefficients under the same assumptions are equivalent, for example

$$\phi_1(i, 0; r; 0) = \phi_2(i, 0; r; \tilde{0}) = \phi_3(i, \tilde{0}; r; 0) = \phi_4(i, \tilde{0}; r; \tilde{0}) = p(X_{i:n} \geq Y_{r:n^*}).$$

- The generality of our work enabled us to compare the values of different future sampling schemes at the same time, and choose the best one corresponding with the practical work.
- Under the same assumptions, the prediction coefficients of future *Krecord* are increasing with K .

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