



Stability analysis of solet effect on thermohaline convection in dusty ferrofluid saturating a Darcy porous medium

R. Sekar *, K. Raju

Department of Mathematics, Pondicherry Engineering College, Pillaichavady, Puducherry – 605 014, India

**Corresponding author E-mail: rsekar@pec.edu*

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Abstract

The Soret-driven ferro thermoconvective instability of multi-component fluid in a porous medium heated from below and salted from above in the presence of dust particles subjected to a transverse uniform magnetic field has been analyzed using Darcy model for various values of permeability of the porous medium. The salinity effect has been contained in magnetization and density of the ferrofluid. A small thermal perturbation imparted on the basic state and a linear stability analysis is used for this model for which normal mode technique is applied. An exact solution is obtained for the case of two free boundaries and both stationary and oscillatory instabilities have been investigated. It is found that the system destabilizes only through stationary mode. The non-buoyancy magnetization parameter, the dust particle parameter and the permeability of the porous medium are found to destabilize the system. The results are depicted graphically.

Keywords: Darcy Model; Ferromagnetic Fluid; Linear Stability Analysis; Soret Parameter; Thermohaline Convection.

1. Introduction

Recent interest in the study of electromagnetic field theory has been motivated by its innumerable applications like satellite communication, TV communication, microwave communication, wireless communication and mobile communication. This theory is also used in analysis and designing of antenna, transmission, Bio-medical system, lines and wave guides, reducing acidity in vegetable to improve taste, weather forecast radars, electric motors, surface hardening, plasmas, remote sensing radars, radiation therapy, lasers, soldering, annealing and masers. Ferrofluids are single-magnetic-domain, two-phase three-component fluids [1], where the core stands for the single domain, core with carrier fluids stands for the two phases, and core with surfactant and carrier fluids stands for three component. Such types of fluids have several applications like mechanical engineering, analytical instrumentation, heat transfer, electronic devices, aerospace, etc and are widely used in rotating X-ray tubes and sealing of computer hard disk drives. These are used as lubricants in bearing and dumpers. In biomedicine field, there is an idea to use ferrofluids for cancer treatment by heating the tumor soaked in ferrofluids by means of an alternating magnetic field. Ferrofluids are suspensions of magnetic nanoparticles whose physical parameters and flows in such fluids could be controlled by an applied magnetic field. The magnetic controlled can be archived by means of magnetic fluid with a strength of the order 10 mT (Odenbach [2]).

In the standard Benard problem, instability is driven by buoyant forces caused by a temperature difference between the upper and lower planes bounding the fluid. If the fluid additionally salt dissolved in it, then there are potentially two destabilizing sources for density difference, the temperature field and salt field. These effects give rise to a convection called thermohaline or double diffusive convection. The Benard convection in ferromagnetic fluids has been well analyzed by various authors such as Rudraiah [3] and Siddheshwar [4].

In many investigations, porous medium is taken to be isotropic for geological and pedological process rarely it forms isotropic media, as is usually assumed in transport studies. Processes such as frost action, sedimentation, compaction and reorientation of solid matrix are responsible for the creation of anisotropic natural porous media.

Rudraiah and Malashetty [5] have analyzed the effect of coupled molecular diffusion on double diffusive convection in a horizontal porous layer by use of finite amplitude method. Later, the study is made for weakly non-linear analysis by Rudraiah and Siddheshwar [6]. Lakshmi Narayana et al. [7] investigated the linear stability analysis of a steady convective double diffusive flow of Hadley type considering the Soret effect which is set up by the horizontal components of temperature and concentration gradient in a shallow horizontal layer of a fluid saturating a porous medium. Bahloul et al. [8] studied numerically and analytically, natural convection in a horizontal Darcy porous layer filled by a binary fluid. In both cases double-diffusive and Soret induced convections were used. The critical Rayleigh numbers for the onset of supercritical, overstable and oscillatory convections were determined in terms of the governing parameters.

In 1970s, Finlayson [9] studied convective instability of ferromagnetic fluid heated from below in the presence of a vertical uniform magnetic field. Further, Vaidyanathan et al. [10] gave the convective instability of ferromagnetic fluid through porous medium of large permeability and mentioned that stationary convection can occur and oscillatory convection cannot occur by use of Brinkman model. This work has been extended to anisotropic porous medium by Sekar et al. [11] and Vaidyanathan et al. [12] modified the above work with use of Darcy model. All the above researches have analyzed the convective instability of a single component fluid. The linear gradients studied on thermohaline convection by Baines and Gill [13]. Vaidyanathan et al. [14, 15] illustrated ferro thermohaline convection in the presence and absence of a porous medium of sparse distribution of two component ferroconvective system. Vaidyanathan et al. [16] attempted to study the Soret effect due to thermoconvective instability in a ferrofluid of a sparse distribution. Sekar et al. [17] further studied the analysis to the condition of a porous medium of ferro convective instability of multi-component fluid heated from below and salted from above using Brinkman model. This work has studied for Darcy model by Sekar et al. [18].

More recently, the presence and absence of rotation on Soret-driven ferrothermohaline convection in an anisotropic porous medium have been investigated by Sekar et al. [19-20] by use of Brinkman model. The temperature dependent viscosity and Soret effects are used in study on thermohaline convection in ferrofluid saturating a porous medium which has been obtained by Sekar and Raju [21]. Sekar and Raju [22] studied the effect of magnetic field dependent viscosity on Soret-driven ferrothermohaline convection in a rotating anisotropic porous medium. This investigation has been worked in the absence of Coriolis force by Sekar and Raju [23]. The effect of dust particles on Soret-driven ferrothermohaline convection in a porous medium has been studied by Sekar et al. [24].

In the present work, the convection of Soret-driven thermohaline instability of multi-component dusty ferrofluid heated from below and salted from above is investigated in a porous medium by use of Darcy model. Using linear stability analysis the conditions for the onset of stationary and oscillatory instabilities have been obtained.

2. Mathematical formulation and governing equations

We consider an infinitely spread layer of an incompressible Boussinesq ferromagnetic fluid of thickness 'd' in the presence of transverse applied magnetic field saturating a densely packed porous medium heated from below and salted from above is considered. The temperature and salinity at the bottom surface $z = -d/2$ are $T_0 + \Delta T/2$ and $S_0 - \Delta S/2$ and the upper surface $T_0 - \Delta T/2$ and $S_0 + \Delta S/2$, respectively. The porous medium is assumed to be densely distributed so that the Darcy model could be used. Both boundaries are taken to be free and perfect conductors of heat and salt. The gravity field $\mathbf{g} = (0, 0, -g)$ and uniform magnetic field intensity $\mathbf{H} = (0, 0, H_0)$ pervade the system. The Soret effect is considered on the temperature gradient. Considering the mathematical equations governing the above investigation in the form (Sekar et al. [17], Chandrasekhar [25]).

$$\nabla \cdot \mathbf{q} = 0 \quad (1)$$

$$\rho_0(\partial/\partial t + \mathbf{q}' \cdot \nabla) \mathbf{q}' = -\nabla p + \rho \mathbf{g} + K'N(\mathbf{q}'_d - \mathbf{q}) + \nabla \cdot (\mathbf{H}\mathbf{B}) - \frac{\mu}{k} \mathbf{q} \quad (2)$$

$$mN \left(\frac{\partial}{\partial t} + \mathbf{q}'_d \cdot \nabla \right) \mathbf{q}'_d = KN(\mathbf{q}'_d - \mathbf{q}) \quad (3)$$

$$\frac{\partial N}{\partial t} + \nabla \cdot (N\mathbf{q}'_d) = 0 \quad (4)$$

$$\left[\rho_0 C_{v,H} - \mu_0 \mathbf{H} (\partial \mathbf{M} / \partial T)_{v,H} \right] (dT/dt) + \mu_0 T (\partial \mathbf{M} / \partial T)_{v,H} \cdot (d\mathbf{H}/dt) \left. \begin{aligned} &+ mNC_{pt} (\partial/\partial t + \mathbf{q}'_d \cdot \nabla) T = K_1 \nabla^2 T + \phi \end{aligned} \right\} \quad (5)$$

$$\left[\rho_0 C_{v,H} - \mu_0 \mathbf{H} (\partial \mathbf{M} / \partial S)_{v,H} \right] (dS/dt) + \mu_0 S (\partial \mathbf{M} / \partial S)_{v,H} \cdot (d\mathbf{H}/dt) \left. \begin{aligned} &+ mNC_{pt} (\partial/\partial t + \mathbf{q}'_d \cdot \nabla) S = K_1 \nabla^2 S + S_T \nabla^2 T \end{aligned} \right\} \quad (6)$$

$$\nabla \cdot \mathbf{B} = 0, \quad \nabla \times \mathbf{H} = 0 \quad (7 \text{ a, b})$$

$$\mathbf{B} = \mu_0(\mathbf{M} + \mathbf{H}) \tag{8}$$

The density equation of state for a two component Boussinesq ferrofluid [17-21] is

$$\rho = \rho_0[1 - \alpha_t(T - T_0) + \alpha_s(S - S_0)] \tag{9}$$

The assumption is made that the magnetization is aligned with magnetic field, but allow a dependence magnitude of magnetic field, temperature and salinity, so that

$$\mathbf{M} = \frac{\mathbf{H}}{H} M(H, T, S). \tag{10}$$

The linearized magnetic equation of state with the corresponding parameter H_0, T_0 and S_0 is

$$M = M_0 + \chi(H - H_0) - K(T - T_0) + K_2(S - S_0), \tag{11}$$

Here H_0 is the uniform magnetic field of the fluid layer when placed in an external magnetic field $\mathbf{H} = H_0^{\text{ext}} \hat{k}$, \hat{k} is a unit vector in the z -direction, H is the magnitude of magnetic field \mathbf{H} and M is the magnitude of the magnetization \mathbf{M} .

The basic state is assumed to be quiescent state and the basic state quantities are obtained by substituting velocity of quiescent state in the constituent equations. The basic state quantities obtained are

$$q_b = 0, \quad \partial T / \partial z = -\beta_t,$$

where β_t is the non-negative constant. Therefore, $T_b = T_0 - \beta_t z$.

Further $\partial S / \partial z = \beta_s$, where β_s is the non-negative constant. Therefore, $S_b = S_0 + \beta_s z$. Taking the components of magnetization and magnetic field in the quiescent state as $[0, 0, M_0(z)]$ and $[0, 0, H_0(z)]$, it is seen that the equation is identically satisfied and Maxwell's equations yields

$$H_0(z) + M_0(z) = C_1, \tag{12}$$

where C_1 is a constant.

Using Eq. (12) in Eqs. (7a) and (8), one gets

$$H_b(z) = \left[H_0 - \frac{K \beta_t z}{1 + \chi} + \frac{K_2 \beta_s z}{1 + \chi} \right] \hat{k}; \quad M_b(z) = \left[M_0 + \frac{K \beta_t z}{1 + \chi} - \frac{K_2 \beta_s z}{1 + \chi} \right] \hat{k}. \tag{13}$$

where spatial variations H_0 and M_0 are taken into account for our analysis.

A small thermal perturbation has been imparted on all the dynamical variables. Let the components of perturbed magnetization and magnetic field can be taken as $[M_1', M_2', M_0(z) + M_3']$ and $[H_1', H_2', H_0(z) + H_3']$, respectively. The perturbed temperature and solute are taken to be

$$T = T_b + T' \quad \text{And} \quad S = S_b + S', \tag{14}$$

where primed quantities denote the perturbation from the quiescent state.

Further analysis has been carried out using the analyses similar to [17-24]. The vertical component of the momentum equation can be written as

$$\left[L_1 \left(\rho_0 \frac{\partial}{\partial t} \right) + m N_0 \frac{\partial}{\partial t} + \frac{\mu}{k} \right] \nabla^2 w = L_1 \left\{ \begin{aligned} & \frac{\mu_0 K \beta_t}{1 + \chi} \nabla_1^2 \left(K(1 - S_T) \theta - (1 + \chi) \frac{\partial}{\partial z} (\phi_1' - \phi_2') \right) \\ & + \frac{\mu_0 K_2 \beta_s}{1 + \chi} \nabla_1^2 \left(K_2 S' + S_T K \theta + (1 + \chi) \frac{\partial}{\partial z} (\phi_1' - \phi_2') \right) \\ & - \frac{\mu_0 K K_2}{1 + \chi} \nabla_1^2 (\beta_s \theta + \beta_t S') + \rho_0 g \alpha_t \nabla_1^2 \theta - \rho_0 g \alpha_s \nabla_1^2 S' \end{aligned} \right\} \tag{15}$$

where $\nabla^2 = (\partial^2 / \partial x^2) + (\partial^2 / \partial y^2) + (\partial^2 / \partial z^2)$ and $\nabla_1^2 = (\partial^2 / \partial x^2) + (\partial^2 / \partial y^2)$.

3. Normal mode analysis method

Analyzing the disturbance into normal modes, one can assume that the perturbation quantities are of the form

$$(w, \theta, \phi, S) = [W(z, t), \Theta(z, t), \phi'(z, t), S'(z, t)] \exp i(k_x x + k_y y) \quad (16)$$

where k_0 is the wave number given by

$$k_0 = \sqrt{k_x^2 + k_y^2}. \quad (17)$$

Following normal mode technique and making use of Eqs. (16) and (17) in Eq. (15), then gives the vertical component of Eq. (2) is can be written as

$$\left\{ L_1 \left(\rho_0 \frac{\partial}{\partial t} \right) + mN_0 \frac{\partial}{\partial t} + \frac{\mu}{k} \right\} \left\{ \frac{\partial^2}{\partial z^2} - k_0^2 \right\} w$$

$$= L_1 \left\{ \begin{aligned} & \frac{\mu_0 K \beta_t k_0^2}{1 + \chi} \left((1 + \chi) \frac{\partial}{\partial z} (\phi_1' - \phi_2') - K(1 - S_T) \theta \right) \\ & - \frac{\mu_0 K_2 \beta_S k_0^2}{1 + \chi} \left(K_2 S' + S_T K \theta + (1 + \chi) \frac{\partial}{\partial z} (\phi_1' - \phi_2') \right) \\ & + \frac{\mu_0 K K_2 k_0^2}{1 + \chi} (\beta_S \theta + \beta_t S') + \rho_0 g \alpha_S k_0^2 S' - \rho_0 g \alpha_t k_0^2 \theta \end{aligned} \right\} \quad (18)$$

The modified Fourier heat conduction equation is

$$L_1 \left\{ \left(\rho C_1 + mN_0 C_{pt} \right) \frac{\partial \theta}{\partial t} \right\} - \mu_0 K T_0 \frac{\partial}{\partial t} \left(\frac{\partial \phi_1'}{\partial z} \right)$$

$$= L_1 \left\{ K_1 \left(\frac{\partial^2}{\partial z^2} - k_0^2 \right) \theta + \left(\rho_0 C_1 \beta_t - \left(\frac{\mu_0 K_2 T_0^2 \beta_t}{1 + \chi} \right) \right) w \right\} + mN_0 C_{pt} \beta_t w \quad (19)$$

The Ficks diffusion equation is

$$L_1 \left\{ \left(\rho C_1' + mN_0 C_{pt} \right) \frac{\partial S}{\partial t} \right\} - \mu_0 K_2 S_0 \frac{\partial}{\partial t} \left(\frac{\partial \phi_2'}{\partial z} \right)$$

$$= L_1 \left\{ K_s \left(\frac{\partial^2}{\partial z^2} - k_0^2 \right) S + S_T \left(\frac{\partial^2}{\partial z^2} - k_0^2 \right) \theta + \left(\rho_0 C_1 \beta_S - \left(\frac{\mu_0 K_2^2 S_0 \beta_S}{1 + \chi} \right) \right) w \right\} + mN_0 C_{pt} \beta_S w \quad (20)$$

where $\rho_0 C_1 = \rho_0 C_{v,H} + \mu_0 K H_0$, $\rho_0 C_1' = \rho_0 C_{v,H} - \mu_0 K_2 H_0$, $L_1 = \left\{ \frac{m}{K} \frac{\partial}{\partial t} + 1 \right\}$.

Following Sunil and Sharma [26] one gets

$$(1 + \chi) \frac{\partial^2 \phi_1'}{\partial z^2} - \left(1 + \frac{M_0}{H_0} \right) k_0^2 \phi_1' - K \frac{\partial \theta}{\partial z} = 0 \quad (21)$$

$$(1 + \chi) \frac{\partial^2 \phi_2'}{\partial z^2} - \left(1 + \frac{M_0}{H_0} \right) k_0^2 \phi_2' - K_2 \frac{\partial S}{\partial z} + S_T K \frac{\partial \theta}{\partial z} = 0. \quad (22)$$

The Eqs. (18)- (22) can be written in non-dimensional form using the non-dimensional numbers and parameters are

$$w^* = \frac{wd}{v}, t^* = \frac{vt}{d^2}, T^* = \left(\frac{K_1 a R^{1/2}}{\rho_0 C_{v,H} \beta_t v d} \right) \theta, \phi_1^* = \left(\frac{(1+\chi) K_1 a R^{1/2}}{\rho_0 C_1 K \beta_t v d^2} \right) \phi_1, \phi_2^* = \left(\frac{(1+\chi) K_s a R_s^{1/2}}{\rho_0 C_1' K_2 \beta_s v d^2} \right) \phi_2, k^* = \frac{k}{d^2},$$

$$S_1 = \frac{\alpha_s S_T}{\alpha_t K_s}, z^* = \frac{z}{d}, a = k_0 d, S^* = \left(\frac{K_s a R_s^{1/2}}{\rho_0 C_1' \beta_s v d} \right) S, D = \frac{\partial}{\partial z^*}, v = \frac{\mu}{\rho_0},$$

The non – dimensional form of governing equations can be written as

$$\left\{ L_1^* \left(\frac{\partial}{\partial t^*} + \frac{1}{k^*} \right) + f \frac{\partial}{\partial t^*} \right\} (D^2 - a^2) w^* = a R^{1/2} L_1^* \left\{ (M_1 D \phi_1^* - M_4 D \phi_1^*) - (1 + (M_1 - M_4)(1 - S_T)) T^* \right\} + a R_s^{1/2} L_1^* \left\{ (M_1' D \phi_2^* - M_4' D \phi_2^*) + (1 - M_1' - M_4') S^* \right\} \quad (23)$$

$$L_1^* P_r \left\{ (1 + h_1) \frac{\partial T^*}{\partial t^*} - M_2 \frac{\partial}{\partial t^*} (D \phi_1^*) \right\} = L_1^* (D^2 - a^2) T^* + a R^{1/2} \left\{ L_1^* (1 - M_2) + h_1 \right\} w^* \quad (24)$$

$$L_1^* P_s \left\{ (1 + h') \frac{\partial S^*}{\partial t^*} - M_2' \frac{\partial}{\partial t^*} (D \phi_2^*) \right\} = L_1^* (D^2 - a^2) S^* + a R_s^{1/2} \left\{ L_1^* (1 - M_2') + h' \right\} w^* + L_1^* S_1 (R / R_s)^{1/2} (D^2 - a^2) T^* \quad (25)$$

$$D^2 \phi_1^* - M_3 a^2 \phi_1^* - D T^* = 0 \quad (26)$$

and

$$D^2 \phi_2^* - M_3 a^2 \phi_2^* - (M_1 / M_4') (R / R_s)^{1/2} D T^* - D S^* = 0 \quad (27)$$

where the dimensionless parameters used are

$$\left. \begin{aligned} M_1 &= \frac{\mu_0 K^2 \beta_t}{(1+\chi) \rho_0 g \alpha_t}, M_2 = \frac{\mu_0 K^2 T}{(1+\chi) \rho_0 C_{v,H}}, M_3 = \frac{1 + M_0 / H_0}{(1+\chi)}, M_4 = \frac{\mu_0 K^2 \beta_s}{(1+\chi) \rho_0 g \alpha_s}, M_5 = \frac{K_2 \beta_s}{K \beta_t}, \\ M_1' &= \frac{\mu_0 K^2 \beta_s}{(1+\chi) \rho_0 g \alpha_s}, M_2' = \frac{\mu_0 K^2 S_0}{(1+\chi) \rho C_1}, M_4' = \frac{\mu_0 K K_2 \beta_t}{(1+\chi) \rho_0 g \alpha_s}, P_r = \frac{v \rho C_1}{K_1}, P_s = \frac{v \rho C_1'}{K_1'}, R_s = \frac{\rho C_1' \beta_s \alpha_s g d^4}{v K_s}, \\ R &= \frac{\rho C_1 \beta_t \alpha_t g d^4}{v K_1}, \tau_1 = \frac{m v}{K d^2}, L_1^* = \left(\tau_1 \frac{\partial}{\partial t^*} + 1 \right), f = \frac{m N_0}{\rho_0}, h_1 = \frac{m N_0 C_{pt}}{\rho C_1}, h' = \frac{m N_0 C_{pt}}{\rho C_1'} \end{aligned} \right\}$$

where R, R_s, P_r, P_s, h_1 and h' are respectively the thermal Rayleigh number, salinity Rayleigh number, the Prandtl numbers and the dust particle parameters.

4. Exact solution for free boundaries

The boundary conditions on velocity, temperature and salinity are

$$w^* = D^2 w^* = T^* = D \phi_1^* = D \phi_2^* = S^* = 0 \text{ At } z^* = \pm 1/2. \quad (28)$$

It may be noted that the solution can be separated into even and odd modes and on expect that even modes will give the lowest eigen value. Hence the solution in which $w^*, T^*, D \phi^*$ are even and ϕ^* is odd.

Following the analysis is similar to [20-24], the exact solutions satisfying Eq. (28) are

$$\begin{aligned}
 w^* &= Ae^{\sigma t^*} \cos \pi z^*, T^* = Be^{\sigma t^*} \cos \pi z^*, D\phi_1^* = Ce^{\sigma t^*} \cos \pi z^*, \\
 \phi_1^* &= \frac{C}{\pi} e^{\sigma t^*} \sin \pi z^*, S^* = Fe^{\sigma t^*} \cos \pi z^*, D\phi_2^* = Ee^{\sigma t^*} \cos \pi z^*, \phi_2^* = \frac{E}{\pi} e^{\sigma t^*} \sin \pi z^*
 \end{aligned} \tag{29}$$

where A, B, C, E and F are constants and σ is the growth rate which is complex constant.

Substituting of Eq. (29) in the Eqs. (23-27), one gets

$$\left. \begin{aligned}
 &\left\{ \left(\sigma + \frac{1}{k} \right) (\tau_1 \sigma + 1) + f \sigma \right\} A - (\tau_1 \sigma + 1) a R^{1/2} (1 + (M_1 - M_4)(1 - S_T)) B \\
 &+ (\tau_1 \sigma + 1) (M_1 - M_4) a R^{1/2} C + (\tau_1 \sigma + 1) (M_1' - M_4') a R_S^{1/2} E \\
 &+ (\tau_1 \sigma + 1) (1 - M_1' - M_4') a R_S^{1/2} F
 \end{aligned} \right\} \tag{30}$$

$$\begin{aligned}
 a R^{1/2} \{ (1 - M_2) (\sigma \tau_1 + 1) + h_1 \} A - (\sigma \tau_1 + 1) \left\{ \text{Pr} (1 + h_1) \sigma + (\pi^2 + a^2) \right\} B \\
 + (\sigma \tau_1 + 1) \text{Pr} M_2 \sigma C = 0
 \end{aligned} \tag{31}$$

$$\begin{aligned}
 a R_S^{1/2} \left\{ (1 - M_2') (\sigma \tau_1 + 1) + h_1' \right\} A - (\sigma \tau_1 + 1) S_1 (R / R_S)^{1/2} (\pi^2 + a^2) B \\
 + (\sigma \tau_1 + 1) M_2' \sigma P_s E - \left\{ (\sigma \tau_1 + 1) \left((\pi^2 + a^2) + P_s (1 + h_1') \right) \right\} F = 0
 \end{aligned} \tag{32}$$

$$-\pi^2 B + (\pi^2 + a^2 M_3) C = 0 \tag{33}$$

$$-S_T (M_1 / M_4') (R / R_S)^{1/2} \pi^2 B + (\pi^2 + a^2 M_3) E - \pi^2 F = 0 \tag{34}$$

For the existence of non-trivial solution the determinant of co-efficient of A, B, C, E and F in Eqs. (30)- (34) must vanish. This determinant on calculation yields

$$T_1 \sigma^4 + T_2 \sigma^3 + T_3 \sigma^2 + T_4 \sigma + T_5 = 0 \tag{35}$$

where

$$T_1 = C_5 + \tau, T_2 = C_1 b_2 \tau + C_2 (C_4 + 2\tau) - C_6 \tau + b_7 C_7 \left\{ \left(\frac{1}{k} + 1 + k \right) + 2\tau^2 \right\} - a^2 \pi^2 R b_2 b_8 S_T C_7 \tau b_4$$

$$\begin{aligned}
 T_3 &= C_1 \left\{ h_1 + b_4 (1 + 2\tau^2) \right\} + C_2 (C_3 + 2\tau C_4 + C_5) - C_6 (2\tau^2 + h_1 + b_4) \\
 &+ b_7 C_7 \left\{ 2\tau \left(\frac{1}{k} + 1 + k \right) + \frac{1}{k} + \tau \right\} + a^2 \pi^2 R b_2 b_8 S_T C_7 (2\tau + h_1 + b_4)
 \end{aligned}$$

$$\begin{aligned}
 T_4 &= C_1 \{ \tau b_4 + 2\tau (h_1 + b_4) \} + C_2 (b_2 + 2\tau b_5) - C_6 (2\tau (h_1 + b_4) + 2\tau) \\
 &+ b_7 C_7 \left(\frac{1 + 2\tau}{k} + 1 + f \right) + a^2 \pi^2 R b_2 b_8 S_T C_7 (2\tau (h_1 + b_4) + \tau b_4)
 \end{aligned}$$

$$T_5 = b_7 \left\{ \begin{array}{l} -a^2 \pi^2 R b_2 (h + b_4) (b_5 + (1 + h') P_s) \\ \left[\begin{array}{l} a b_3 R_S^{1/2} \left(a b_5 (h' + b_6) R_S^{1/2} - \frac{a R (h_1 + b_4) b_5 S_1}{R_S^{1/2}} \right) \\ -b_7 \left[\begin{array}{l} -(b_5 + (1 + h') P_s) \left(\frac{-b_5}{k} + a^2 R (h_1 + b_4) S_2 \right) \end{array} \right] \end{array} \right\} - a^2 \pi^2 R b_2 b_7 b_8 (h_1 + b_4) (b_5 + (1 + h') P_s) S_T$$

$$C_1 = -a^2 \pi^2 R (b_5 + (1+h')P_s), C_2 = -b_7 b_3 R_S a, C_3 = (h' + b_6) b_5, C_4 = b_5 b_6 \tau + (h' + b_6)(1 + h_1 \text{Pr}), \\ C_5 = \tau b_6 (1 + h_1) \text{Pr}, C_6 = a R b_3 b_5 b_7 S_1,$$

$$b_1 = M_1 - M_4, b_2 = M_1' - M_4', b_3 = 1 - M_1' + M_4', b_4 = 1 - M_2, b_5 = \pi^2 + a^2, b_6 = 1 - M_2', \\ b_7 = \pi^2 + a^2 M_3, b_8 = M_1 / M_4', S_2 = 1 + (b_1(1 - S_T)).$$

For obtaining stationary instability, the time-independent term T_5 is equal to zero. From Eq. (35) it is easy to get the Rayleigh number R_c .

$$R_c = \frac{b_5 \left\{ a^2 b_3 R_S (h' + b_6) + \frac{1}{k} (b_5 + (1+h')P_s) \right\}}{a^2 (h + b_6) \left\{ b_3 b_5 S_1 + b_9 (b_5 + (1+h')P_s) \right\} - \frac{a^2 \pi^2}{b_7} (h + b_4) (b_5 + (1+h')P_s)}$$

Making use of $\sigma = i \sigma_1$ in Eq. (35) leads to Rayleigh number for oscillatory instability and following Refs. [17]-[24].

$$R_{oc} = (Y_1 Y_3 + Y_4 Y_2) / (Y_1^2 + Y_2^2)$$

where

$$Y_1 = B_1 \sigma_1^2 + B_2, Y_2 = B_3 \sigma_1^3 + B_4 \sigma, Y_3 = A_1 + A_2 \sigma_1^2 + A_3, Y_4 = A_4 \sigma_1^3 + A_5 \sigma, \sigma_1^2 = \frac{X_1 \pm \sqrt{X_1^2 - X_2 X_3}}{X_4},$$

$$B_1 = a^2 \pi^2 b_2 b_8 C_7 S_T ((h_1 + b_4) + 2\tau), B_2 = a^2 (b_5 + (1+h')P_s) (h_1 + b_4) (\pi^2 b_7 (b_1 + b_2 b_8 S_T) + S_2)$$

$$B_3 = a^2 \pi^2 b_2 b_4 b_8 C_7 S_T \tau, B_4 = b_7 C_7 \left(\frac{2\tau + 1}{k} + 1 + f \right) + a^2 \pi^2 b_2 b_8 S_T C_7 (2\tau (h_1 + b_4) + \tau b_4)$$

$$A_1 = C_5 + \tau,$$

$$A_2 = \left\{ C_1 ((h_1 + b_4) + 2\tau^2 b_4) + C_2 (C_3 + 2\tau C_4 + C_5) - C_6 (2\tau^2 + h_1 + b_4) + b_7 C_7 \left(2\tau \left(\frac{1}{k} + 1 + f \right) + \frac{1}{k} + \tau \right) \right\}$$

$$A_3 = -b_5 \left\{ a^2 b_3 b_7^2 R_S (h' + b_6) + \frac{1}{k} (b_5 + (1+h')P_s) \right\}$$

$$A_4 = - \left\{ C_1 \tau b_4 + C_2 (C_4 + 2\tau) - C_6 \tau + b_7 C_7 \left(\left(\frac{1}{k} + 1 + f \right) + 2\tau^2 \right) \right\}$$

$$A_5 = C_1 (2\tau (h_1 + b_4) + \tau b_4) + C_2 (2\tau b_5 + b_2) - C_6 ((h_1 + b_4) 2\tau + \tau)$$

$$X_1 = -(B_1 A_5 + B_2 A_4 + B_4 A_2 + B_3 A_3), X_2 = 4(B_1 B_2 + B_4 A_1 + B_2 A_2), X_3 = B_5 A_2 + B_4 A_3, X_4 = 2(B_1 B_2 + B_4 A_1 + B_2 A_2)$$

5. Results and discussion

By considering Darcy model, the role of Soret effect on thermohaline convection in dusty ferrofluid saturating a porous medium in the presence of a uniform vertical magnetic field is investigated theoretically for different permeabilities in the range of 0.001–0.009 [18]. The present analysis has been carried out through stationary and oscillatory instabilities. The physical properties contributing to the non-linear effect have been omitted as the perturbation is small and a linear stability analysis is discussed.

The dust particle parameter h_1 is assumed to take values from 1 to 7 [24], the range of salinity Rayleigh number R_S is varied from 0 to 400, the Soret parameter S_T is assumed to take values from -0.002 to 0.002, and M_4 , M_5 , and M_6 are assumed to be 0.1 [24]. The magnetization parameter M_1 is a ratio of magnetic to gravitational forces. M_1 is taken to be 1000 [19]. For a very large value of M_1 , the effect of magnetic mechanism is very large in comparison with buoyancy effect [17-20]. M_2 is assumed to have negligible value for these types of fluids and hence taken to be zero [21]. The non-buoyancy magnetization parameter M_3 is in the range of values from 5 to 25 because M_3 cannot take value less than one [14-19]. The ratio of momentum diffusivity and thermal diffusivity (Prandtl number P_s) is assumed to be 0.01 and 0.001.

Fig. 1 represents the critical magnetic Rayleigh number R_c versus dust particle parameter h_1 for different values of permeability of the porous medium k , $R_S = 100$ and $S_T = -0.002$. When h_1 is increased from 1 to 7, there is a fall in R_c due to decreasing effect of salt on the convective system. This leads to destabilize the system and the cell shape leading asymptotic trend. Moreover, it is clear that large values of permeability favors early onset of instability. Also, the larger permeability, greater the pore size tending the fluid to attain greater percolation velocity and it favors early onset of convection.

In Fig. 2, the effect of non-buoyancy magnetization parameter M_3 increases from 5 to 25, the critical magnetic Rayleigh number R_c decreases, for different dust particle parameter h_1 . Thus the system gets destabilized. It is clear that, when M_3 increases from 5 to 25, R_c decreases, indicating the onset of instability. This is because the high magnetization tends to release large energy to the system causing instability to set in earlier. When $k = 0.001$ and $h_1 = 1$, R_c gets the highest values, thus the system have high energy on the onset of convection which is depicted in Figs. 1 and 2.

From Fig. 3, the cell shape and critical magnetic Rayleigh number R_c with respect to k , indicate that the system destabilizes. This is indicated by decrease in R_c . It is observed from Figs. 4 and 5 that increase in h_1 destabilizes the system, when increasing values of Salinity Rayleigh number R_S and Soret parameter S_T , respectively. Also, when increasing values of R_S from 0 to 400 and S_T from -0.002 to 0.002 with respect to h_1 , critical magnetic Rayleigh number R_c gets the same and various effects.

In Fig. 6, the variation of R_c versus h_1 for various values of P_s is shown. It is clear that there is a destabilization when both h_1 and P_s are increased. Fig. 7 indicates the variation of R_c versus M_3 for different h_1 . When increasing M_3 from 5 to 25 and h_1 from 1 to 7, R_c is decreased. Thus, the system gets destabilization. The same effect is seen in Fig. 8. The magnetization of the fluid is found to destabilize the system through stationary mode.

Fig. 8 shows the variation of R_c with respect to k for various R_S , when R_S increases from 0 to 400 and k increases from 0.001 to 0.009, there is a decrease in R_c promoting instability. It is clear that the system has a destabilizing behavior. Fig. 9 gives the critical wave number a_c versus M_3 for different k . When $k = 0.001, 0.003$ and 0.005 , the critical wave number a_c gets the same values and it lead to decreasing trend. It shows also that the system has a destabilizing effect. But, when $k = 0.007$ and 0.009 , system gets various energy, it lead to parabolic form and converges to the same point. Fig. 10 represents variation of a_c versus S_T for different k . It is clear that the system gets non-equilibrium position through oscillatory mode. Due to the increasing of salt on the system for various k , the convection of the ferrofluid has transcendental form and it is not much pronounced with the thermal effect.

In some situation, the convective system has a form of oscillation which is depicted in Figs. 9 and 10 through the critical wave number a_c . In the presence of non-buoyancy magnetization parameter M_3 , the convective ferromagnetic fluid gets an oscillation which is rather pronounced. But, introduce of Soret effect on the same, the system gets more oscillation is much pronounced in comparison with the Fig. 9. Therefore the system gets more destabilized because of wave nature of ferrofluid and due to this the Soret effect dominates the system.

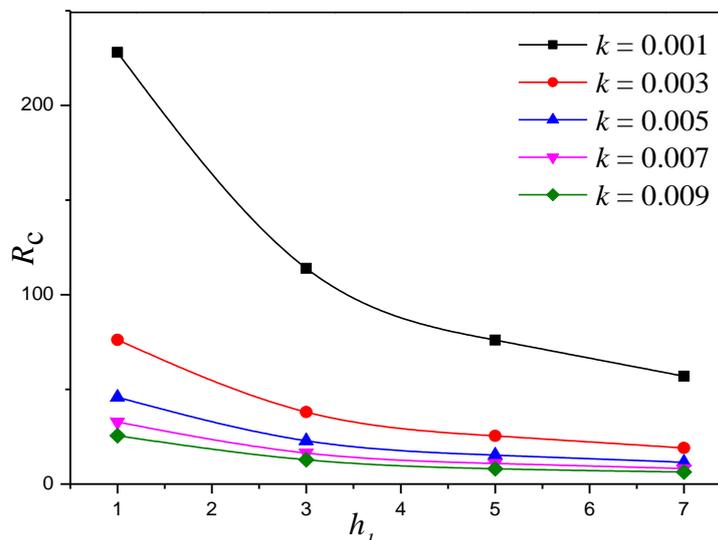


Fig. 1: Variation of R_c versus h_1 for different of k , $M_3 = 5$, $P_s = 0.01$, $R_S = 100$ and $S_T = -0.002$.

6. Conclusion

The linear stability of Soret driven thermohaline convection in ferromagnetic fluid layer heated from below and salted from above saturating a porous medium subjected to a transverse uniform magnetic field has been considered. In this analysis, we have investigated the effect of various parameters like permeability of the porous medium, non-buoyancy magnetization, buoyancy magnetization, magnetic numbers, dust particle parameter, Prandtl number, thermal Rayleigh

number and salinity Rayleigh number on the onset of convection. Also the principle of exchange of instability is applied to find out the mode of attaining instability.

We see that convection can encourage in a ferromagnetic fluid by means of spatial variation in magnetization, which is induced when the magnetization of the ferrofluid depends on temperature and salinity. For the stationary convection, when increasing value of porous medium, there is a decreasing convection process on the system. From the figures, one can conclude that the non-buoyancy magnetization parameter, dust particle parameter, porous and Soret effects have destabilizing behavior and the Soret effect dominate the system which is depicted in Fig. 10.

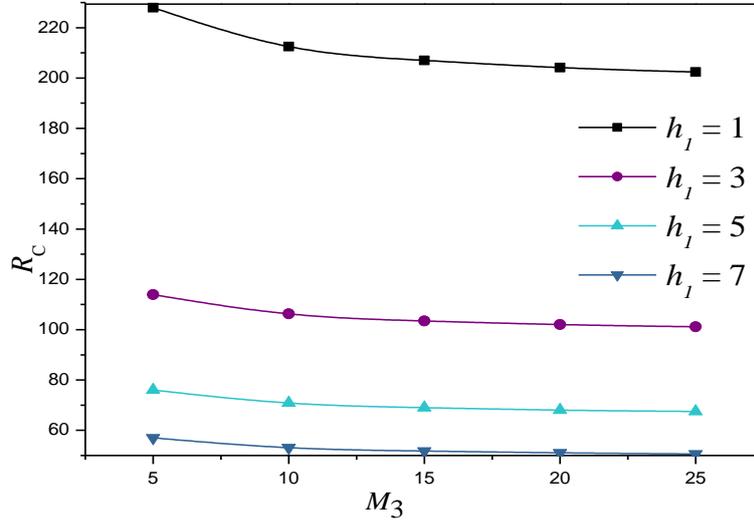


Fig. 2: Variation of R_c versus M_3 for different values of h_1 , $P_s = 0.01$, $k = 0.001$, $R_s = 100$ and $S_T = -0.002$.

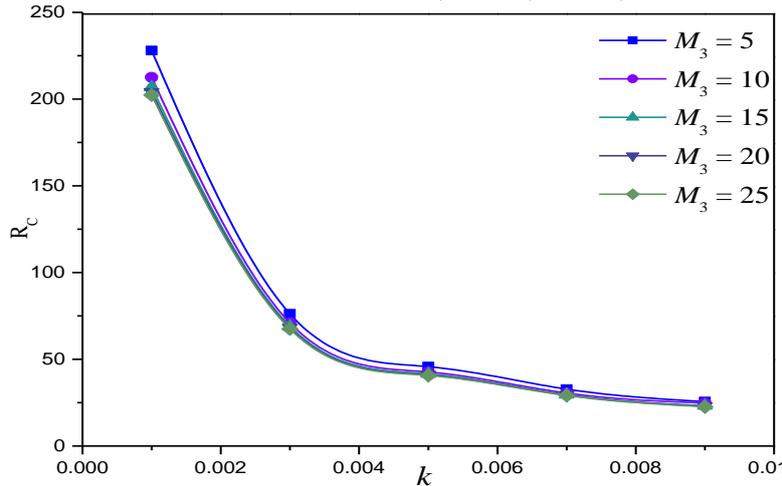


Fig. 3: Variation of R_c versus k for different values of M_3 , $P_s = 0.01$, $h_1 = 1$, $R_s = 100$ and $S_T = -0.002$.

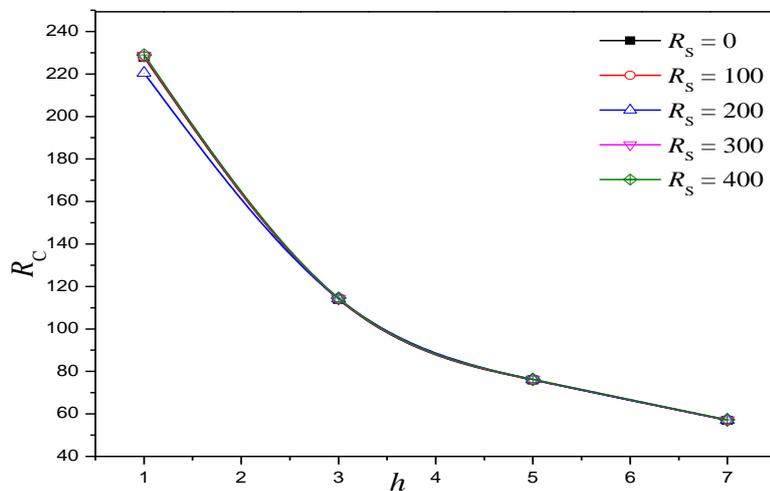


Fig. 4: Variation of R_c Versus h_1 for different values of R_s , $P_s = 0.01$, $M_3 = 5$, $k = 0.001$ and $S_T = -0.002$.

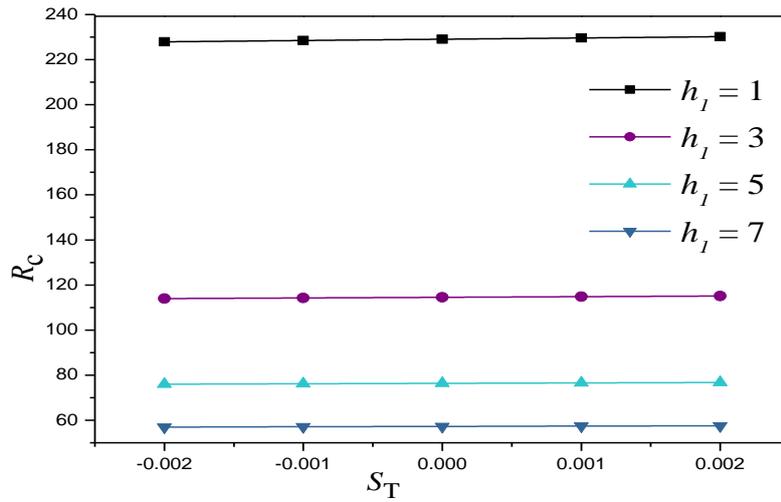


Fig. 5: Variation of R_C versus S_T for different values of h_1 , $P_s = 0.01$, $k = 0.001$, $M_3 = 5$ and $R_S = 100$.

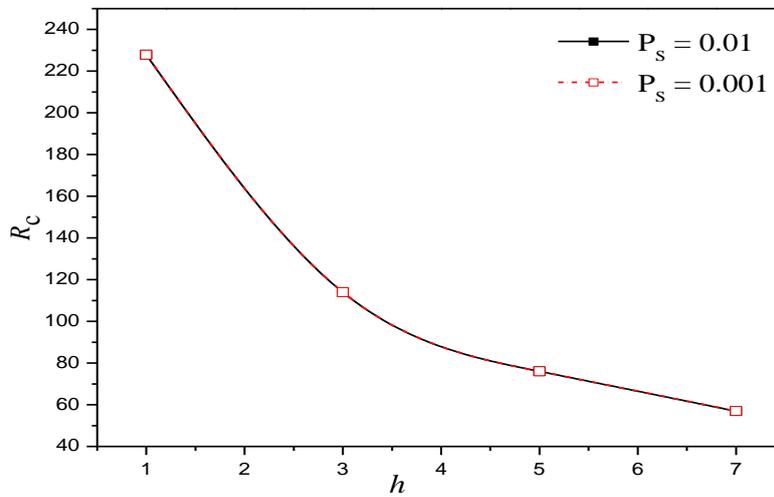


Fig. 6: Variation of R_C versus h_1 for different values of P_s , $k = 0.001$, $M_3 = 5$, $S_T = -0.002$ and $R_S = 100$.

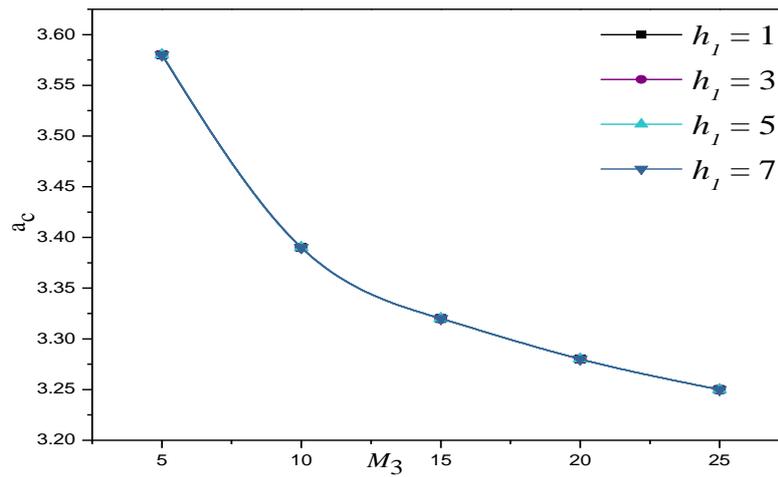


Fig. 7: Variation of a_c versus M_3 for different values of h_1 , $k = 0.001$, $P_s = 0.01$, $S_T = -0.002$ and $R_S = 100$.

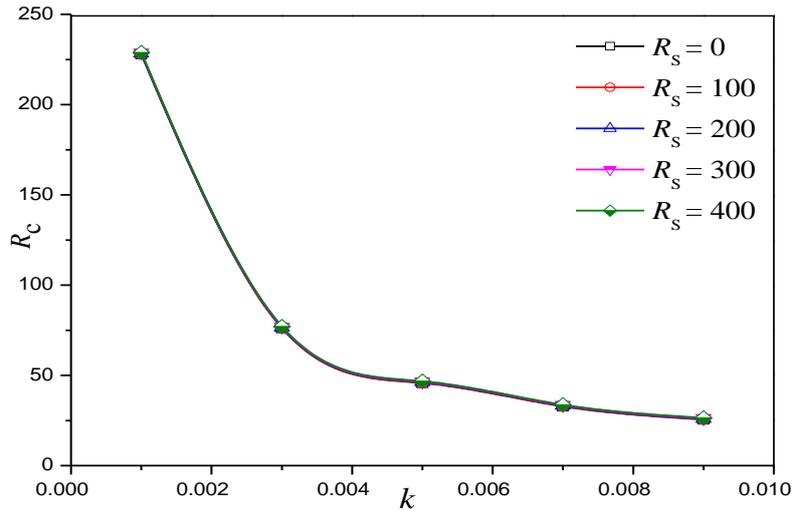


Fig. 8: Variation of R_c versus k for different values of R_s , $M_3 = 5$, $h_1 = 1$, $P_s = 0.01$, $S_T = -0.002$ and $R_s = 100$.

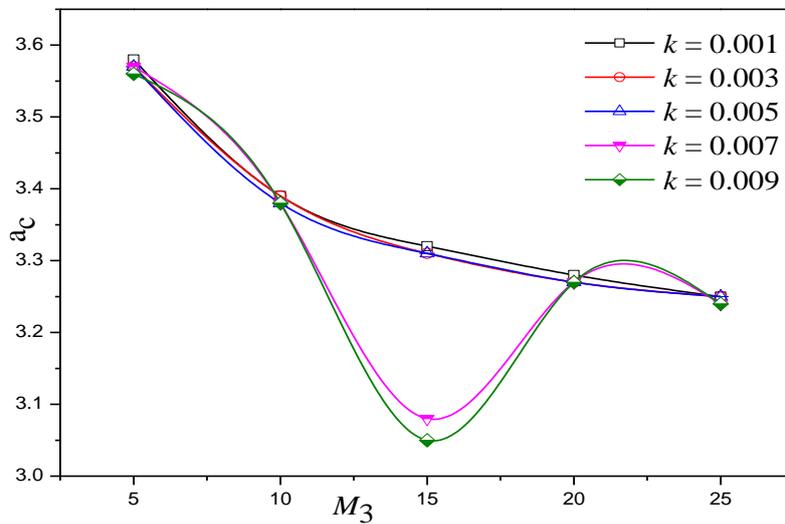


Fig. 9: Variation of a_c versus M_3 for different values of k , $P_s = 0.01$, $h_1 = 1$, $S_T = -0.002$ and $R_s = 100$.

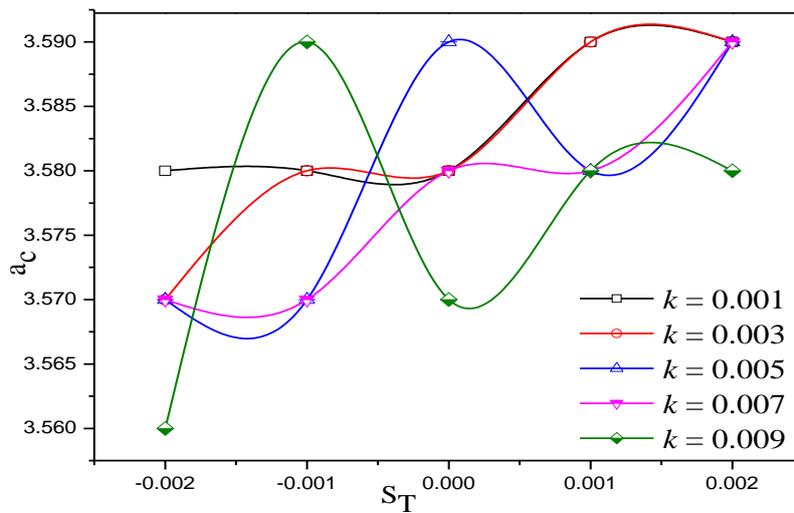


Fig. 10: Variation of a_c versus S_T for different values of k , $M_3 = 5$, $h_1 = 1$, $P_s = 0.01$ and $R_s = 100$.

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